



# Some Properties of Kenmotsu Manifolds Admitting a New Type of Semi-Symmetric Non-Metric Connection

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**Abstract.** In this paper, we study some properties of Kenmotsu manifolds admitting a semi-symmetric non-metric connection. Some curvature's properties of Kenmotsu manifolds that admits a semi-symmetric non-metric connection are obtained. Semi-symmetric, Ricci semi-symmetric and locally  $\phi$ -symmetric conditions for Kenmotsu manifolds with respect to semi-symmetric non-metric connection are also studied. It is proved that the manifold endowed with a semi-symmetric non-metric connection is regular. We obtain some conditions for semi-symmetric and Ricci semi-symmetric Kenmotsu manifolds endowed with semi-symmetric non-metric connection  $\tilde{\nabla}$ . It is further observed that the Ricci soliton of data  $(g, \xi, \Theta)$  are expanding and shrinking respectively for semi-symmetric and Ricci semi-symmetric Kenmotsu manifolds admitting a semi-symmetric non-metric connection.

**Keywords.** Kenmotsu manifold, Semi-symmetric non-metric connection, Semi-symmetric manifold, Ricci semi-symmetric manifold, Locally  $\phi$ -symmetric Kenmotsu manifold, Curvature tensor, Ricci tensor, Einstein manifold

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## 1. Introduction

The investigations of a differentiable manifold with contact and almost contact metric structures had been initiated by Boothby and Wang [5]. A class of almost contact metric manifold and named as Kenmotsu manifold has been initiated by Kenmotsu [16]. Further, the characteristics of Kenmotsu manifolds have been investigated by many authors such as Sinha and Srivastava [23], Chaubey and Yildiz [6], Chaubey and Ojha [8], Chaubey and Yadav [9], Özgür and De [19] and many others. The main invariants of an affine connection are its torsion and curvature (Friedmann and Schouten [14]). A torsion tensor of a connection is defined as under

$$\mathcal{T}(\mathcal{K}_1, \mathcal{K}_2) = \nabla_{\mathcal{K}_1} \mathcal{K}_2 - \nabla_{\mathcal{K}_2} \mathcal{K}_1 - [\mathcal{K}_1, \mathcal{K}_2], \quad \text{for all } \mathcal{K}_1, \mathcal{K}_2 \in \mathfrak{X}(\mathfrak{M}), \quad (1.1)$$

where  $\mathfrak{X}(\mathfrak{M})$  is a set of all smooth vector fields on  $\mathfrak{M}$ . A connection  $\nabla$  is symmetric and non-symmetric according as  $\mathcal{T}(\mathcal{K}_1, \mathcal{K}_2) = 0$ , and  $\mathcal{T}(\mathcal{K}_1, \mathcal{K}_2) \neq 0$ , respectively. The idea of semi-symmetric connection on a differentiable manifold has been proposed by Friedmann and Schouten [14]. A linear connection  $\tilde{\nabla}$  on  $\mathfrak{M}^n$  is called semi-symmetric if

$$\tilde{\mathcal{T}}(\mathcal{K}_1, \mathcal{K}_2) = \eta(\mathcal{K}_2)\mathcal{K}_1 - \eta(\mathcal{K}_1)\mathcal{K}_2, \quad \text{for all } \mathcal{K}_1, \mathcal{K}_2 \in \mathfrak{X}(\mathfrak{M}), \quad (1.2)$$

where  $\eta$  is a 1-form associated with the vector field  $\xi$  and satisfies

$$\eta(\mathcal{K}_1) = g(\mathcal{K}_1, \xi), \quad \text{for all } \mathcal{K}_1, \mathcal{K}_2 \in \mathfrak{X}(\mathfrak{M}). \quad (1.3)$$

Further, the idea of metric connection with torsion on a Riemannian manifold has been initiated by Hayden. A connection  $\nabla$  is metric and non-metric on  $\mathfrak{M}$  according as  $\nabla g = 0$  and  $\nabla g \neq 0$ , respectively, where  $g$  is a Riemannian metric in  $\mathfrak{M}$ . The idea of semi-symmetric non-metric connection has been initiated by Agashe and Chafle [1]. The quarter-symmetric connection in a differentiable manifold with affine connection has been investigated by Golab [15]. Further, characteristics of quarter-symmetric metric connection have been investigated by several geometers like Rastogi [22], Mishra and Pandey [18], Yano and Imai [28], Kumar *et al.* [17], and many others. The semi-symmetric non-metric connection in a Kenmotsu manifold has been investigated by Tripathi and Nakkar [26]. In line with this, Chaubey and Yildiz [6] initiated another semi-symmetric non-metric connection. Later on some other authors, like De and Pathak [10], Pankaj *et al.* [20, 21] studied several connections. Tripathi [25] has justified the presence of a new connection and showed that in special cases.

We have decided by above investigations to study characteristics of Kenmotsu manifolds admitting a semi-symmetric non-metric connection. Section 1 is introductory. Section 2 is concerned with some basic results of Kenmotsu manifolds. The necessary results of a semi-symmetric non-metric connection are given in Section 3. Basic characteristics of Riemannian curvature tensor with respect to a semi-symmetric non-metric connection have been investigated in Section 4. Semi-symmetric Kenmotsu manifolds admitting a semi-symmetric non-metric connection have been investigated in Section 5. Ricci semi-symmetric Kenmotsu manifolds admitting a semi-symmetric non-metric connection have been investigated in Section 6. Locally  $\phi$ -symmetric Kenmotsu manifolds admitting a semi-symmetric non-metric connection have been investigated in Section 7. In Section 8, we give an example.

## 2. Preliminaries

Suppose  $\mathfrak{M}$  be an  $(2n + 1)$ -dimensional almost contact metric manifolds with an almost contact metric quartet  $(\phi, \xi, \eta, g)$  consisting of a  $(1, 1)$  tensor field  $\phi$ , a vector field  $\xi$ , a 1-form  $\eta$  and the Riemannian metric  $g$  on  $\mathfrak{M}$  satisfying [3, 27]:

$$\eta(\xi) = 1, \quad \phi(\xi) = 0, \quad \eta(\phi(\mathcal{K}_1)) = 0, \quad g(\mathcal{K}_1, \xi) = \eta(\mathcal{K}_1), \quad (2.1)$$

$$\phi^2(\mathcal{K}_1) = -\mathcal{K}_1 + \eta(\mathcal{K}_1)\xi, \quad g(\mathcal{K}_1, \phi\mathcal{K}_2) = -g(\phi\mathcal{K}_1, \mathcal{K}_2), \quad (2.2)$$

$$g(\phi\mathcal{K}_1, \phi\mathcal{K}_2) = g(\mathcal{K}_1, \mathcal{K}_2) - \eta(\mathcal{K}_1)\eta(\mathcal{K}_2). \quad (2.3)$$

An almost contact metric quartet  $(\phi, \xi, \eta, g)$  is a Kenmotsu manifolds [16] iff

$$(\nabla_{\mathcal{K}_1}\phi)(\mathcal{K}_2) = g(\phi\mathcal{K}_1, \mathcal{K}_2)\xi - \eta(\mathcal{K}_2)\phi\mathcal{K}_1. \quad (2.4)$$

It is also defined by above investigations.

$$\nabla_{\mathcal{K}_1}\xi = \mathcal{K}_1 - \eta(\mathcal{K}_1)\xi, \quad (2.5)$$

$$(\nabla_{\mathcal{K}_1}\eta)(\mathcal{K}_2) = g(\mathcal{K}_1, \mathcal{K}_2) - \eta(\mathcal{K}_1)\eta(\mathcal{K}_2) = g(\phi\mathcal{K}_1, \phi\mathcal{K}_1), \quad (2.6)$$

$$\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\xi = \eta(\mathcal{K}_1)\mathcal{K}_2 - \eta(\mathcal{K}_2)\mathcal{K}_1, \quad (2.7)$$

$$\mathfrak{R}(\xi, \mathcal{K}_1)\mathcal{K}_2 = \eta(\mathcal{K}_2)\mathcal{K}_1 - g(\mathcal{K}_1, \mathcal{K}_2)\xi, \quad (2.8)$$

$$\mathfrak{R}(\xi, \mathcal{K}_1)\xi = \mathcal{K}_1 - \eta(\mathcal{K}_1)\xi, \quad (2.9)$$

$$\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) = g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2) - g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1), \quad (2.10)$$

$$\mathfrak{S}(\phi\mathcal{K}_1, \phi\mathcal{K}_2) = \mathfrak{S}(\mathcal{K}_1, \mathcal{K}_2) + 2n\eta(\mathcal{K}_1)\eta(\mathcal{K}_2), \quad (2.11)$$

$$\mathfrak{S}(\mathcal{K}_1, \xi) = -2n\eta(\mathcal{K}_1), \quad (2.12)$$

$$\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_2) = g(\Omega\mathcal{K}_1, \mathcal{K}_2), \quad (2.13)$$

$\forall \mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3 \in \mathfrak{X}(\mathfrak{M})$ , where  $\mathfrak{X}(\mathfrak{M})$  is a set of all smooth vector fields on  $\mathfrak{M}$  and  $\mathfrak{R}$ ,  $\mathfrak{S}$  and  $\Omega$  represent the curvature tensor, Ricci tensor and Ricci operator of the manifold  $\mathfrak{M}$ , respectively, with respect to the Levi-Civita connection  $\nabla$ .

**Definition 2.1.** An almost contact metric manifold  $\mathfrak{M}$  is said to be an  $\eta$ -Einstein manifolds if there exists the real valued functions  $\Theta_1, \Theta_2$  such that

$$\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_2) = \Theta_1g(\mathcal{K}_1, \mathcal{K}_2) + \Theta_2\eta(\mathcal{K}_1)\eta(\mathcal{K}_2). \quad (2.14)$$

For  $\Theta_2 = 0$ , the manifold  $\mathfrak{M}$  is an Einstein manifolds.

**Definition 2.2.** A Ricci soliton  $(g, \mathcal{V}, \Theta)$  on a Riemannian manifold is defined by

$$\mathcal{L}_{\mathcal{V}}g + 2\mathfrak{S} + 2\Theta g = 0, \quad (2.15)$$

on  $\mathfrak{M}$ , where  $\mathcal{L}_{\mathcal{V}}g$  is a Lie-derivative along the vector field  $\mathcal{V}$  of metric  $g$  and  $\Theta \in \mathbb{R}$ . The Ricci soliton  $(g, \mathcal{V}, \Theta)$  is shrinking, steady and expanding whenever,  $\Theta < 0$ ,  $\Theta = 0$  and  $\Theta > 0$ , respectively [2].

**Definition 2.3.** The Ricci tensor  $\mathfrak{S}$  of a Kenmotsu manifolds is said to be  $\eta$ -parallel if it satisfies

$$(\nabla_{\mathcal{K}_1}\mathfrak{S})(\phi\mathcal{K}_2, \phi\mathcal{K}_3) = 0. \quad (2.16)$$

The idea of Ricci  $\eta$ -parallelity for Sasakian manifolds was investigated by Yano and Kon [27]. In [11] the authors proved that a 3-dimensional Kenmotsu manifold has  $\eta$ -parallel Ricci tensor iff it is of constant scalar curvature.

### 3. A Semi-Symmetric Non-Metric Connection

Let us define, a linear connection  $\tilde{\nabla}$  [4, 13] as

$$\tilde{\nabla}_{\mathcal{K}_1}\mathcal{K}_2 = \nabla_{\mathcal{K}_1}\mathcal{K}_2 + \frac{1}{2}[\eta(\mathcal{K}_2)\mathcal{K}_1 - \eta(\mathcal{K}_1)\mathcal{K}_2] \quad (3.1)$$

satisfying

$$\tilde{\mathcal{T}}(\mathcal{K}_1, \mathcal{K}_2) = \eta(\mathcal{K}_2)\mathcal{K}_1 - \eta(\mathcal{K}_1)\mathcal{K}_2, \quad (3.2)$$

and

$$(\tilde{\nabla}_{\mathcal{K}_1}g)(\mathcal{K}_2, \mathcal{K}_3) = \frac{1}{2}[2\eta(\mathcal{K}_1)g(\mathcal{K}_2, \mathcal{K}_3) - \eta(\mathcal{K}_2)g(\mathcal{K}_1, \mathcal{K}_3) - \eta(\mathcal{K}_3)g(\mathcal{K}_1, \mathcal{K}_2)]. \quad (3.3)$$

for arbitrary vector fields  $\mathcal{K}_1$ ,  $\mathcal{K}_2$  and  $\mathcal{K}_3$  is said to be a semi-symmetric non-metric connection. Also, we have

$$(\tilde{\nabla}_{\mathcal{K}_1}\phi)(\mathcal{K}_2) = \frac{1}{2}[2(\nabla_{\mathcal{K}_1}\phi)(\mathcal{K}_2) - \eta(\mathcal{K}_2)\phi(\mathcal{K}_1)], \quad (3.4)$$

$$(\tilde{\nabla}_{\mathcal{K}_1}\eta)(\mathcal{K}_2) = (\nabla_{\mathcal{K}_1}\eta)(\mathcal{K}_2), \quad (3.5)$$

$$(\tilde{\nabla}_{\mathcal{K}_1}g)(\phi\mathcal{K}_1, \mathcal{K}_3) = \frac{1}{2}[2\eta(\mathcal{K}_1)g(\phi\mathcal{K}_2, \mathcal{K}_3) - \eta(\mathcal{K}_3)g(\mathcal{K}_1, \phi\mathcal{K}_2)]. \quad (3.6)$$

On replacing  $\mathcal{K}_2$  by  $\xi$  in the equation (3.1), we have

$$\tilde{\nabla}_{\mathcal{K}_1}\xi = \frac{3}{2}\nabla_{\mathcal{K}_1}\xi. \quad (3.7)$$

On replacing  $\mathcal{K}_1$  by  $\xi$  in the equation (3.3), we have

$$(\tilde{\nabla}_{\xi}g)(\mathcal{K}_2, \mathcal{K}_3) = g(\phi\mathcal{K}_2, \phi\mathcal{K}_3) = (\nabla_{\mathcal{K}_2}\eta)(\mathcal{K}_3). \quad (3.8)$$

Hence we have the following propositions:

**Proposition 3.1.** *The vector field  $\xi$  with respect to  $\nabla$  and  $\tilde{\nabla}$  is related by equation (3.7).*

**Proposition 3.2.** *Co-variant differentiation of  $g$  with respect to contra-variant vector field  $\xi$  is given by the equation (3.8) in a contact metric manifold admitting connection  $\tilde{\nabla}$ .*

The curvature tensor  $\tilde{\mathfrak{R}}$  of  $\tilde{\nabla}$  defined as follows

$$\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 = \tilde{\nabla}_{\mathcal{K}_1}\tilde{\nabla}_{\mathcal{K}_2}\mathcal{K}_3 - \tilde{\nabla}_{\mathcal{K}_2}\tilde{\nabla}_{\mathcal{K}_1}\mathcal{K}_3 - \tilde{\nabla}_{[\mathcal{K}_1, \mathcal{K}_2]}\mathcal{K}_3, \quad (3.9)$$

where  $\mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3 \in \mathfrak{X}(\mathfrak{M})$ .

Using equation (3.1) in (3.9), we have

$$\begin{aligned} \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 + \frac{1}{2}[(\nabla_{\mathcal{K}_1}\eta)(\mathcal{K}_3)\mathcal{K}_2 - (\nabla_{\mathcal{K}_1}\eta)(\mathcal{K}_2)\mathcal{K}_3 \\ &\quad - (\nabla_{\mathcal{K}_2}\eta)(\mathcal{K}_3)\mathcal{K}_1 + (\nabla_{\mathcal{K}_2}\eta)(\mathcal{K}_1)\mathcal{K}_3] \\ &\quad + \frac{1}{4}[\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathcal{K}_1 - \eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathcal{K}_2], \end{aligned} \quad (3.10)$$

where

$$\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 = \nabla_{\mathcal{K}_1}\nabla_{\mathcal{K}_2}\mathcal{K}_3 - \nabla_{\mathcal{K}_2}\nabla_{\mathcal{K}_1}\mathcal{K}_3 - \nabla_{[\mathcal{K}_1, \mathcal{K}_2]}\mathcal{K}_3 \quad (3.11)$$

is the Riemannian curvature tensor [3] of  $\nabla$ .

**Proposition 3.3.** *The relation between Riemannian curvature tensors  $\tilde{\mathfrak{R}}$  and  $\mathfrak{R}$  with respect to connections  $\tilde{\nabla}$  and  $\nabla$ , respectively is given by the equation (3.10).*

#### 4. Some Curvature Tensor of Kenmotsu Manifolds With a Semi-Symmetric Non-Metric Connection

Now using equation (2.6) in equation (3.10), we have

$$\begin{aligned} \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 + \frac{1}{2}[g(\mathcal{K}_1, \mathcal{K}_3)\mathcal{K}_2 - g(\mathcal{K}_2, \mathcal{K}_3)\mathcal{K}_1] \\ &\quad + \frac{3}{4}[\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathcal{K}_1 - \eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathcal{K}_2]. \end{aligned} \quad (4.1)$$

Contracting of (4.1) with respect to  $\mathcal{K}_1$ , we have

$$\tilde{\mathfrak{S}}(\mathcal{K}_2, \mathcal{K}_3) = \mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) - ng(\mathcal{K}_2, \mathcal{K}_3) + \frac{3}{2}n\eta(\mathcal{K}_2)\eta(\mathcal{K}_3). \quad (4.2)$$

Using (2.13) in equation (4.2), we have

$$\tilde{\mathfrak{Q}}\mathcal{K}_2 = \mathfrak{Q}\mathcal{K}_2 - n(\mathcal{K}_1) + \frac{3}{2}n\eta(\mathcal{K}_2)\xi. \quad (4.3)$$

Again contracting equation (4.2), we have

$$\tilde{\mathfrak{r}} = \mathfrak{r} - \frac{n}{2}(4n - 1), \quad (4.4)$$

where  $\tilde{\mathfrak{S}}(\mathcal{K}_2, \mathcal{K}_3)$ ;  $\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3)$ ,  $\tilde{\mathfrak{Q}}$ ;  $\mathfrak{Q}$  and  $\tilde{\mathfrak{r}}$ ;  $\mathfrak{r}$  are the Ricci tensors, Ricci operators and scalar curvatures of  $\tilde{\nabla}$  and  $\nabla$ .

On replacing  $\mathcal{K}_1$  by  $\xi$  in (4.1) and using (2.1), (2.2), we have

$$\tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_3 = \mathfrak{R}(\xi, \mathcal{K}_2)\mathcal{K}_3 - \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)\xi + \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\xi - \frac{1}{4}\eta(\mathcal{K}_3)\mathcal{K}_2. \quad (4.5)$$

In view of (2.8) and (4.5), we have

$$\tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_3 = \frac{3}{4}[-2g(\mathcal{K}_2, \mathcal{K}_3)\xi + \eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\xi + \eta(\mathcal{K}_3)\mathcal{K}_2]. \quad (4.6)$$

Again on replacing  $\mathcal{K}_3$  by  $\xi$  in (4.1) and using (2.1), (2.7), we have

$$\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\xi = \frac{3}{4}\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\xi = -\frac{3}{4}\tilde{\mathfrak{T}}(\mathcal{K}_1, \mathcal{K}_2) \neq 0. \quad (4.7)$$

Thus, we have the following theorem:

**Theorem 4.1.** *Every  $(2n + 1)$ -dimensional Kenmotsu manifold admitting connection  $\tilde{\nabla}$  is regular.*

Now operating  $\eta$  on both sides of equation (4.1) and using equation (2.1), we have

$$\begin{aligned} \eta(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) &= \frac{1}{2}[2g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2) - 2g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1) \\ &\quad + g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2) - g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1)]. \end{aligned} \quad (4.8)$$

On contracting of (4.7) with respect to  $\mathcal{K}_1$ , we have

$$\tilde{\mathfrak{S}}(\mathcal{K}_2, \xi) = -\frac{3}{2}n\eta(\mathcal{K}_2). \quad (4.9)$$

In view of equations (4.2), (4.3) and (4.4), we have the following lemma:

**Lemma 4.1.** *In a Kenmotsu manifold Ricci tensor, Ricci operator and scalar curvature with respect to connections  $\tilde{\nabla}$  and  $\nabla$  are related by the equations (4.2), (4.3) and (4.4).*

*Proof.* On taking  $\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 = 0$  in the equation (4.1), we have

$$\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 = -\frac{1}{2}[g(\mathcal{K}_1, \mathcal{K}_3)\mathcal{K}_2 - g(\mathcal{K}_2, \mathcal{K}_3)\mathcal{K}_1] - \frac{3}{4}[\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathcal{K}_1 - \eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathcal{K}_2]. \quad (4.10)$$

Thus

$$\begin{aligned} \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3, \mathcal{K}_4) &= -\frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_3)g(\mathcal{K}_2, \mathcal{K}_4) + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)g(\mathcal{K}_1, \mathcal{K}_4) \\ &\quad - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)g(\mathcal{K}_1, \mathcal{K}_4) + \frac{3}{4}\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)g(\mathcal{K}_2, \mathcal{K}_4). \end{aligned} \quad (4.11)$$

Contracting of (4.11) with respect to vector field  $\mathcal{K}_1$ , we have

$$S(\mathcal{K}_2, \mathcal{K}_3) = ng(\mathcal{K}_2, \mathcal{K}_3) - \frac{3}{2}n\eta(\mathcal{K}_2)\eta(\mathcal{K}_3). \quad (4.12)$$

Using equation (2.13) in equation (4.12), we have

$$\Omega\mathcal{K}_2 = n\mathcal{K}_2 - \frac{3}{2}n\eta(\mathcal{K}_2)\xi. \quad (4.13)$$

Again contracting equation (4.12), we have

$$\tau = \frac{n}{2}(4n - 1). \quad (4.14)$$

□

By virtue of Definition 2.1 and equation (4.12), we state the theorem:

**Theorem 4.2.** *If Riemannian curvature tensor with respect to connection  $\tilde{\nabla}$  in a Kenmotsu manifold vanishes, then the manifold is an  $\eta$ -Einstein manifold.*

## 5. Semi-Symmetric Kenmotsu Manifolds

A  $(2n + 1)$ -dimensional Kenmotsu manifold  $\mathfrak{M}$  with  $\tilde{\nabla}$  is said to be semi-symmetric [20] if

$$(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\tilde{\mathfrak{R}})(\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 = 0,$$

i.e.

$$\begin{aligned} \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 - \tilde{\mathfrak{R}}(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 \\ - \tilde{\mathfrak{R}}(\mathcal{K}_3, \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4)\mathcal{K}_5 - \tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_5 = 0. \end{aligned} \quad (5.1)$$

On replacing  $\mathcal{K}_1$  by  $\xi$ , we have

$$\begin{aligned} \tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 - \tilde{\mathfrak{R}}(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 \\ - \tilde{\mathfrak{R}}(\mathcal{K}_3, \tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_4)\mathcal{K}_5 - \tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_5 = 0. \end{aligned} \quad (5.2)$$

In view of equations (2.1), (2.2), (4.6), (4.7) and (4.8), we have

$$\begin{aligned}
 \tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4, \mathcal{K}_5, \mathcal{K}_2) &= g(\mathcal{K}_2, \mathcal{K}_3)\eta(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_4)\mathcal{K}_5) - \frac{1}{2}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\eta(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_4)\mathcal{K}_5) \\
 &\quad + \frac{1}{2}\eta(\mathcal{K}_3)\eta(\tilde{\mathfrak{R}}(\mathcal{K}_2, \mathcal{K}_4)\mathcal{K}_5) - g(\mathcal{K}_2, \mathcal{K}_4)\eta(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_3)\mathcal{K}_5) \\
 &\quad + \frac{1}{2}\eta(\mathcal{K}_2)\eta(\mathcal{K}_4)\eta(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_3)\mathcal{K}_5) + \frac{1}{2}\eta(\mathcal{K}_4)\eta(\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_2)\mathcal{K}_5) \\
 &\quad + g(\mathcal{K}_2, \mathcal{K}_5)\eta(\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\xi) - \frac{1}{2}\eta(\mathcal{K}_2)\eta(\mathcal{K}_5)\eta(\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\xi) \\
 &\quad + \frac{1}{2}\eta(\mathcal{K}_5)\eta(\tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_2).
 \end{aligned}
 \tag{5.3}$$

By using equations (2.1), (2.2), (4.6), (4.7) and (4.8), we have

$$\begin{aligned}
 \tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4, \mathcal{K}_5, \mathcal{K}_2) &= -\frac{3}{2}g(\mathcal{K}_2, \mathcal{K}_3)g(\mathcal{K}_4, \mathcal{K}_5) + \frac{3}{2}g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_4)\eta(\mathcal{K}_5) - \frac{3}{4}\eta(\mathcal{K}_4)\eta(\mathcal{K}_5) \\
 &\quad + \frac{3}{2}g(\mathcal{K}_4, \mathcal{K}_5)g(\mathcal{K}_5, \mathcal{K}_3) - \frac{9}{4}g(\mathcal{K}_4, \mathcal{K}_2)\eta(\mathcal{K}_5)\eta(\mathcal{K}_3).
 \end{aligned}
 \tag{5.4}$$

Hence, we have

$$\begin{aligned}
 \tilde{\mathfrak{R}}(\mathcal{K}_3, \mathcal{K}_4)\mathcal{K}_5 &= -\frac{3}{2}g(\mathcal{K}_4, \mathcal{B}_5)\mathcal{K}_3 + \frac{3}{2}\eta(\mathcal{K}_4)\eta(\mathcal{K}_5)\mathcal{K}_3 - \frac{3}{4}\eta(\mathcal{K}_4)\eta(\mathcal{K}_5) + \frac{3}{2}g(\mathcal{K}_5, \mathcal{K}_3)\mathcal{K}_4 \\
 &\quad - \frac{9}{4}\eta(\mathcal{K}_5)\eta(\mathcal{K}_3)\mathcal{K}_4.
 \end{aligned}
 \tag{5.5}$$

Contracting equation (5.5) with respect to  $\mathcal{K}_3$ , we have

$$\tilde{\mathfrak{S}}(\mathcal{K}_4, \mathcal{K}_5) = -3ng(\mathcal{K}_4, \mathcal{K}_5) + \frac{3}{2}(2n - 1)\eta(\mathcal{K}_4)\eta(\mathcal{K}_5).
 \tag{5.6}$$

Using equation (4.2) in above equation, we obtain

$$\mathfrak{S}(\mathcal{K}_4, \mathcal{K}_5) = -2ng(\mathcal{K}_4, \mathcal{K}_5) + \frac{3}{2}(n - 1)\eta(\mathcal{K}_4)\eta(\mathcal{K}_5).
 \tag{5.7}$$

Using equation (2.13) in above equation, we have

$$\Omega\mathcal{K}_4 = -2n\mathcal{K}_4 + \frac{3}{2}(n - 1)\eta(\mathcal{K}_4)\xi.
 \tag{5.8}$$

Again contracting equation (5.7), we obtain

$$\mathfrak{r} = -\frac{1}{2}(8n^2 + n + 3).
 \tag{5.9}$$

By virtue of Definition 2.1 and equation (5.7), we can state

**Theorem 5.1.** *A semi-symmetric Kenmotsu manifold admitting connection  $\tilde{\nabla}$  is an  $\eta$ -Einstein manifold.*

The Ricci soliton of data  $(g, \mathcal{V}, \Theta)$  is defined by (2.15), where  $g, \mathcal{V}, \Theta$  are Riemannian metric, a vector field and a real constant. Here two conditions come out with regard to the  $\mathcal{V} : \mathcal{V} \in \text{span}\{\xi\}$  and  $\mathcal{V} \perp \text{span}\{\xi\}$ . Now taking  $\mathcal{V} \in \text{span}\{\xi\}$ . The Ricci soliton of data  $(g, \xi, \Theta)$  on a Kenmotsu manifold admitting connection  $\tilde{\nabla}$  defined as under:

$$(\tilde{\mathfrak{L}}_\xi g)(\mathcal{K}_1, \mathcal{K}_2) + 2\tilde{\mathfrak{S}}(\mathcal{K}_1, \mathcal{K}_2) + 2\Theta g(\mathcal{K}_1, \mathcal{K}_2) = 0.
 \tag{5.10}$$

$\forall \mathcal{K}_1, \mathcal{K}_2 \in \mathfrak{X}(\mathcal{M})$ . Here  $\tilde{\mathcal{L}}_\xi g$ , the Lie-derivative of  $g$  with respect to  $\xi$  admitting connection  $\tilde{\nabla}$ , is defined as under

$$(\tilde{\mathcal{L}}_\xi g)(\mathcal{K}_1, \mathcal{K}_2) = g(\tilde{\nabla}_{\mathcal{K}_1} \xi, \mathcal{K}_2) + g(\mathcal{K}_1, \tilde{\nabla}_{\mathcal{K}_2} \xi) - 2g(\phi \mathcal{K}_1, \phi \mathcal{K}_2). \quad (5.11)$$

Now, using equations (2.1), (2.3), (2.5), (3.7) and (5.11), we have

$$(\tilde{\mathcal{L}}_\xi g)(\mathcal{K}_1, \mathcal{K}_2) = g(\phi \mathcal{K}_1, \phi \mathcal{K}_2). \quad (5.12)$$

Using equations (5.6) and (5.12) in the equation (5.10), we have

$$g(\phi \mathcal{K}_1, \phi \mathcal{K}_2) - 6ng(\mathcal{K}_1, \mathcal{K}_2) + 3(2n - 1)\eta(\mathcal{K}_1)\eta(\mathcal{K}_2) + 2\Theta g(\mathcal{K}_1, \mathcal{K}_2) = 0. \quad (5.13)$$

On taking  $\mathcal{K}_1 = \mathcal{K}_2 = \xi$  and using (2.1) in (5.13), we have

$$\Theta = \frac{3}{2} > 0. \quad (5.14)$$

Thus, we state the theorem:

**Theorem 5.2.** *A semi-symmetric Kenmotsu manifold admitting connection  $\tilde{\nabla}$ , the Ricci soliton of data  $(g, \xi, \Theta)$  is always expanding.*

## 6. Ricci Semi-Symmetric Kenmotsu Manifolds

A  $(2n + 1)$ -dimensional contact metric manifolds  $\mathcal{M}$  with respect to connection  $\tilde{\nabla}$  is said to be Ricci semi-symmetric [20] if

$$(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2) \cdot \tilde{\mathfrak{S}})(\mathcal{K}_3, \mathcal{K}_4) = 0.$$

i.e.

$$\tilde{\mathfrak{S}}(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4) + \tilde{\mathfrak{S}}(\mathcal{K}_3, \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4) = 0. \quad (6.1)$$

On replacing  $\mathcal{K}_1$  by  $\xi$  and using (4.6) in (6.1), we have

$$\tilde{\mathfrak{S}}(\tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4) + \tilde{\mathfrak{S}}(\mathcal{K}_3, \tilde{\mathfrak{R}}(\xi, \mathcal{K}_2)\mathcal{K}_4) = 0, \quad (6.2)$$

i.e.

$$\begin{aligned} & -\frac{3}{2}g(\mathcal{K}_2, \mathcal{K}_3)\tilde{\mathfrak{S}}(\xi, \mathcal{K}_4) + \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\tilde{\mathfrak{S}}(\xi, \mathcal{K}_4) - \frac{3}{4}\eta(\mathcal{K}_3)\tilde{\mathfrak{S}}(\mathcal{K}_2, \mathcal{K}_4) - \frac{3}{2}g(\mathcal{K}_2, \mathcal{K}_4)\tilde{\mathfrak{S}}(\mathcal{K}_3, \xi) \\ & + \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_4)\tilde{\mathfrak{S}}(\mathcal{K}_3, \xi) - \frac{3}{4}\eta(\mathcal{K}_4)\tilde{\mathfrak{S}}(\mathcal{K}_3, \mathcal{K}_2) = 0. \end{aligned} \quad (6.3)$$

In view of equation (4.9), the above equation yields

$$\begin{aligned} & \frac{9}{4}ng(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_4) - \frac{9}{8}n\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4) - \frac{3}{4}\eta(\mathcal{K}_3)\tilde{\mathfrak{S}}(\mathcal{K}_2, \mathcal{K}_4) + \frac{9}{4}ng(\mathcal{K}_2, \mathcal{K}_4)\eta(\mathcal{K}_3) \\ & - \frac{9}{8}n\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4) - \frac{3}{4}\eta(\mathcal{K}_4)\tilde{\mathfrak{S}}(\mathcal{K}_3, \mathcal{K}_2) = 0. \end{aligned} \quad (6.4)$$

Again replacing  $\mathcal{K}_4$  by  $\xi$  and using (4.9) in (6.4), we have

$$\tilde{\mathfrak{S}}(\mathcal{K}_2, \mathcal{K}_3) = 3ng(\mathcal{K}_2, \mathcal{K}_3) + \frac{3}{2}n\eta(\mathcal{K}_2)\eta(\mathcal{K}_3). \quad (6.5)$$

Using (4.2) in (6.5), we have

$$\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) = 4ng(\mathcal{K}_2, \mathcal{K}_3). \quad (6.6)$$



On contracting equation (6.6), we have

$$r = 4n(2n + 1), \quad (6.7)$$

with the help of equation (6.7), equation (4.4) takes the form

$$\tilde{r} = \frac{3n}{2}(4n + 3). \quad (6.8)$$

In view of equation (6.6), we can state following:

**Theorem 6.1.** *A Ricci semi-symmetric Kenmotsu manifold equipped with connection  $\tilde{\nabla}$  is an Einstein manifold.*

Using equation (4.1) in the given below equation

$$(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2) \cdot \tilde{\mathfrak{S}})(\mathcal{K}_3, \mathcal{K}_4) = -\tilde{\mathfrak{S}}(\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4) - \tilde{\mathfrak{S}}(\mathcal{K}_3, \tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4), \quad (6.9)$$

we have

$$\begin{aligned} (\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2) \cdot \tilde{\mathfrak{S}})(\mathcal{K}_3, \mathcal{K}_4) &= (\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2) \cdot \mathfrak{S})(\mathcal{K}_3, \mathcal{K}_4) - \frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_4) \\ &\quad + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_4) - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_4) \\ &\quad + \frac{3}{4}\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_4) - \frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_4)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) \\ &\quad + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_4)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_4)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) \\ &\quad + \frac{3}{4}\eta(B_1)\eta(\mathcal{K}_4)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) - \frac{3}{2}n \cdot \eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3)\eta(\mathcal{K}_4) \\ &\quad - \frac{3}{2}n \cdot \eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4)\eta(\mathcal{K}_3). \end{aligned} \quad (6.10)$$

If we assume  $(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2) \cdot \mathfrak{S})(\mathcal{K}_3, \mathcal{K}_4) = (\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2) \cdot \tilde{\mathfrak{S}})(\mathcal{K}_3, \mathcal{K}_4)$ , then from equation (6.10), we have

$$\begin{aligned} &-\frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_4) + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_4) - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \mathcal{K}_4) \\ &+ \frac{3}{4}\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_4) - \frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_4)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_4)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) \\ &- \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_4)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) + \frac{3}{4}\eta(\mathcal{K}_1)\eta(\mathcal{K}_4)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) - \frac{3}{2}n\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3)\eta(\mathcal{K}_4) \\ &- \frac{3}{2}n\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4)\eta(\mathcal{K}_3) = 0, \end{aligned} \quad (6.11)$$

where

$$(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2) \cdot \mathfrak{S})(\mathcal{K}_3, \mathcal{K}_4) = -\mathfrak{S}(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3, \mathcal{K}_4) - \mathfrak{S}(\mathcal{K}_3, \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4). \quad (6.12)$$

Now, replacing  $\mathcal{K}_4$  by  $\xi$  in the equation (6.11), we have

$$\begin{aligned} &-\frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \xi) + \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \xi) - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_1, \xi) + \frac{3}{4}\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathfrak{S}(\mathcal{K}_2, \xi) \\ &- \frac{1}{2}g(\mathcal{K}_1, \xi)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) + \frac{1}{2}g(\mathcal{K}_2, \xi)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) - \frac{3}{4}\eta(\mathcal{K}_2)\eta(\xi)\mathfrak{S}(\mathcal{K}_3, \mathcal{K}_1) + \frac{3}{4}\eta(\mathcal{K}_1)\eta(\xi)\mathfrak{S}(\mathcal{K}_2, \mathcal{K}_3) \\ &- \frac{3}{2}n\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3)\eta(\xi) - \frac{3}{2}n\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\xi)\eta(\mathcal{K}_3) = 0. \end{aligned} \quad (6.13)$$

Now, using equations (2.1), (2.10) and (6.5) in equation (6.13), we have

$$-3ng(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2) - \frac{3}{2}ng(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2) + 3ng(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1) + \frac{3}{2}ng(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1) = 0, \quad (6.14)$$

i.e.

$$\frac{9}{2}n[\eta(\mathcal{K}_1)g(\mathcal{K}_2, \mathcal{K}_3) - \eta(\mathcal{K}_2)g(\mathcal{K}_1, \mathcal{K}_3)] = 0, \quad (6.15)$$

which is not possible. Hence we have the following:

**Corollary 6.1.** *In a Ricci semi-symmetric Kenmotsu manifold admitting connection  $\tilde{\nabla}$*

$$(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2) \cdot \mathfrak{S})(\mathcal{K}_3, \mathcal{K}_4) \neq (\tilde{\mathfrak{R}}(\mathcal{K}_1, \mathcal{K}_2) \cdot \tilde{\mathfrak{S}})(\mathcal{K}_3, \mathcal{K}_4). \quad (6.16)$$

Using equations (5.12) and (6.5) in the equation (5.10), we have

$$2(3n + \Theta)g(\mathcal{K}_1, \mathcal{K}_2) + g(\phi\mathcal{K}_1, \phi\mathcal{K}_2) + 3n\eta(\mathcal{K}_1)\eta(\mathcal{K}_2) = 0. \quad (6.17)$$

On taking  $\mathcal{K}_1 = \mathcal{K}_2 = \xi$  and using (2.1) in (6.17), we have

$$\Theta = -\frac{9n}{2} < 0. \quad (6.18)$$

Thus, we have the following:

**Theorem 6.2.** *A Ricci semi-symmetric Kenmotsu manifold admitting connection  $\tilde{\nabla}$ , the Ricci soliton of data  $(g, \xi, \Theta)$  is always shrinking.*

## 7. Locally $\phi$ -Symmetric Kenmotsu Manifolds

**Definition 7.1.** A Kenmotsu manifolds  $\mathfrak{M}$  admitting connection  $\tilde{\nabla}$  is called locally  $\phi$ -symmetric [24] if

$$\phi^2((\tilde{\nabla}_{\mathcal{K}_4} \tilde{\mathfrak{R}})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) = 0$$

$\forall \mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3, \mathcal{K}_4$  are orthogonal to  $\xi$ .

Taking covariant differentiation of  $\mathfrak{R}$  with respect to  $\mathcal{K}_4$ , we have

$$\begin{aligned} (\tilde{\nabla}_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= \tilde{\nabla}_{\mathcal{K}_4} \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 - \mathfrak{R}(\tilde{\nabla}_{\mathcal{K}_4} \mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 \\ &\quad - \mathfrak{R}(\mathcal{K}_1, \tilde{\nabla}_{\mathcal{K}_4} \mathcal{K}_2)\mathcal{K}_3 - \mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)(\tilde{\nabla}_{\mathcal{K}_4} \mathcal{K}_3). \end{aligned} \quad (7.1)$$

Now using equations (2.10) and (3.1) in equation (7.1), we have

$$\begin{aligned} (\tilde{\nabla}_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= (\nabla_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 + \frac{1}{2}[2\eta(\mathcal{K}_4)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 - \eta(\mathcal{K}_1)\mathfrak{R}(\mathcal{K}_4, \mathcal{K}_2)\mathcal{K}_3 \\ &\quad - \eta(\mathcal{K}_2)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_4)\mathcal{K}_3 - \eta(\mathcal{K}_3)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4 + g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2)\mathcal{K}_4 \\ &\quad - g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1)\mathcal{K}_4]. \end{aligned} \quad (7.2)$$

Applying covariant differentiation on (4.1) with respect to  $\mathcal{K}_4$ , we have

$$\begin{aligned} (\tilde{\nabla}_{\mathcal{K}_4} \tilde{\mathfrak{R}})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= (\tilde{\nabla}_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 + \frac{1}{2}[(\tilde{\nabla}_{\mathcal{K}_4} g)(\mathcal{K}_1, \mathcal{K}_3)\mathcal{K}_2 - (\tilde{\nabla}_{\mathcal{K}_4} g)(\mathcal{K}_2, \mathcal{K}_3)\mathcal{K}_1] \\ &\quad + \frac{3}{4}[(\tilde{\nabla}_{\mathcal{K}_4} \eta)(\mathcal{K}_2)\eta(\mathcal{K}_3)\mathcal{K}_1 + (\tilde{\nabla}_{\mathcal{K}_4} \eta)(\mathcal{K}_3)\eta(\mathcal{K}_2)\mathcal{K}_1 - (\tilde{\nabla}_{\mathcal{K}_4} \eta)(\mathcal{K}_1)\eta(\mathcal{K}_3)\mathcal{K}_2 \\ &\quad - (\tilde{\nabla}_{\mathcal{K}_4} \eta)(\mathcal{K}_3)\eta(\mathcal{K}_1)\mathcal{K}_2]. \end{aligned} \quad (7.3)$$

Using equations (2.6), (3.3), (3.5) and (7.2), we have

$$\begin{aligned}
 (\tilde{\nabla}_{\mathcal{K}_4} \tilde{\mathfrak{R}})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 &= (\nabla_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 + \frac{1}{2}[2\eta(\mathcal{K}_4)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 - \eta(\mathcal{K}_1)\mathfrak{R}(\mathcal{K}_4, \mathcal{K}_2)\mathcal{K}_3 \\
 &\quad - \eta(\mathcal{K}_2)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_4)\mathcal{K}_3 - \eta(\mathcal{K}_3)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4 + g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_2)\mathcal{K}_4 \\
 &\quad - g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_1)\mathcal{K}_4] + \frac{1}{2}g(\mathcal{K}_1, \mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_2 - \frac{1}{2}g(\mathcal{K}_2, \mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_1 \\
 &\quad - g(\mathcal{K}_4, \mathcal{K}_1)\eta(\mathcal{K}_3)\mathcal{K}_2 + g(\mathcal{K}_4, \mathcal{K}_2)\eta(\mathcal{K}_3)\mathcal{K}_1 - g(\mathcal{K}_4, \mathcal{K}_3)\eta(\mathcal{K}_1)\mathcal{K}_2 \\
 &\quad + g(\mathcal{K}_4, \mathcal{K}_3)\eta(\mathcal{K}_2)\mathcal{K}_1 - \frac{3}{2}\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_1 + \frac{3}{2}\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_1.
 \end{aligned}
 \tag{7.4}$$

Now applying  $\phi^2$  on both sides of equation (7.4) and using equation (2.2), we have

$$\begin{aligned}
 \phi^2((\tilde{\nabla}_{\mathcal{K}_4} \tilde{\mathfrak{R}})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) &= \phi^2((\nabla_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) + \frac{1}{2}[-2\eta(\mathcal{K}_4)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3 \\
 &\quad + 2\eta(\mathcal{K}_4)\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3)\xi + \eta(\mathcal{K}_1)\mathfrak{R}(\mathcal{K}_4, \mathcal{K}_2)\mathcal{K}_3 \\
 &\quad - \eta(\mathcal{K}_1)\eta(\mathfrak{R}(\mathcal{K}_4, \mathcal{K}_2)\mathcal{K}_3)\xi + \eta(\mathcal{K}_2)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_4)\mathcal{K}_3 \\
 &\quad - \eta(\mathcal{K}_2)\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_4)\mathcal{K}_3)\xi + \eta(\mathcal{K}_3)\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\xi \\
 &\quad - \eta(\mathcal{K}_3)\eta(\mathfrak{R}(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_4)\xi - \eta(\mathcal{K}_2)g(\mathcal{K}_1, \mathcal{K}_3)\mathcal{K}_4 \\
 &\quad + 2\eta(\mathcal{K}_2)\eta(\mathcal{K}_4)g(\mathcal{K}_1, \mathcal{K}_3)\xi + \eta(\mathcal{K}_1)g(\mathcal{K}_2, \mathcal{K}_3)\mathcal{K}_4 \\
 &\quad - 2\eta(\mathcal{K}_1)\eta(\mathcal{K}_4)g(\mathcal{K}_2, \mathcal{K}_3)\xi - \eta(\mathcal{K}_4)g(\mathcal{K}_1, \mathcal{K}_3)\mathcal{K}_2 \\
 &\quad + \eta(\mathcal{K}_4)g(\mathcal{K}_2, \mathcal{K}_3)\mathcal{K}_1 + 2\eta(\mathcal{K}_3)g(\mathcal{K}_1, \mathcal{K}_4)\mathcal{K}_2 \\
 &\quad - 2\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)g(\mathcal{K}_1, \mathcal{K}_4)\xi - 2\eta(\mathcal{K}_3)g(\mathcal{K}_2, \mathcal{K}_4)\mathcal{K}_1 \\
 &\quad + 2\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)g(\mathcal{K}_2, \mathcal{K}_4)\xi + 2\eta(\mathcal{K}_1)g(\mathcal{K}_4, \mathcal{K}_3)\mathcal{K}_2 \\
 &\quad - 2\eta(\mathcal{K}_2)g(\mathcal{K}_4, \mathcal{K}_3)\mathcal{K}_1 + 3\eta(\mathcal{K}_2)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_1 \\
 &\quad - 3\eta(\mathcal{K}_1)\eta(\mathcal{K}_3)\eta(\mathcal{K}_4)\mathcal{K}_2].
 \end{aligned}
 \tag{7.5}$$

Taking  $\mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3$  and  $\mathcal{K}_4$  orthogonal to  $\xi$ , then from equation (7.5), we have

$$\phi^2((\tilde{\nabla}_{\mathcal{K}_4} \tilde{\mathfrak{R}})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3) = \phi^2((\nabla_{\mathcal{K}_4} \mathfrak{R})(\mathcal{K}_1, \mathcal{K}_2)\mathcal{K}_3).
 \tag{7.6}$$

**Theorem 7.1.** *The necessary and sufficient condition for a Kenmotsu manifold to be locally  $\phi$ -symmetric with respect to connection  $\tilde{\nabla}$  is that the manifold is also locally  $\phi$ -symmetric with respect to the connection  $\nabla$ .*

### 8. Example of a Three-Dimensional Kenmotsu Manifold

Let three-dimensional manifold  $\mathfrak{M}^3 = \{(t_1, t_2, t_3) \in \mathbb{R}^3 : t_3 > 0\}$ , where  $(t_1, t_2, t_3)$  are the standard co-ordinates in  $\mathbb{R}^3$ . The vector fields [12]

$$\varsigma_1 = t_3 \frac{\partial}{\partial t_1}, \quad \varsigma_2 = t_3 \frac{\partial}{\partial t_2}, \quad \varsigma_3 = -t_3 \frac{\partial}{\partial t_3}$$

are linearly independent at each point of  $\mathfrak{M}$ . Let  $g$  be the Riemannian metric defined by

$$\left. \begin{aligned} g(\zeta_1, \zeta_2) = g(\zeta_2, \zeta_3) = g(\zeta_3, \zeta_1) = 0, \\ g(\zeta_1, \zeta_1) = g(\zeta_2, \zeta_2) = g(\zeta_3, \zeta_3) = 1, \end{aligned} \right\} \quad (8.1)$$

where

$$g = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Let  $\eta$  be the 1-form defined by  $\eta(\mathcal{K}_1) = g(\mathcal{K}_1, \zeta_3)$  for any  $\mathcal{K}_1 \in \mathfrak{X}(\mathfrak{M})$ . Let  $\phi$  be the (1,1)-tensor field defined by

$$(\phi\zeta_1) = -\zeta_2, \quad (\phi\zeta_2) = \zeta_1, \quad (\phi\zeta_3) = 0. \quad (8.2)$$

Now for  $\mathcal{K}_1 = \mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2 + \mathcal{K}_1^3\zeta_3$  and  $\xi = \zeta_3$ , using linearity of  $\phi$  and  $g$ , we have

$$\eta(\zeta_3) = \eta(\xi) = 1, \quad \phi^2(\mathcal{K}_1) = -\mathcal{K}_1 + \eta(\mathcal{K}_1)\zeta_3 = -(\mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2) \quad (8.3)$$

where  $\mathcal{K}_1^1, \mathcal{K}_1^2, \mathcal{K}_1^3$  are the scalars and  $\forall \mathcal{K}_1, \mathcal{K}_2 \in \mathfrak{X}(\mathfrak{M})$ . Thus for  $\zeta_3 = \xi$ ,  $(\phi, \xi, \eta, g)$  defines an almost contact metric structure on  $\mathfrak{M}$ . Let  $\nabla$  be the Levi-Civita connection with respect to the metric  $g$ . Then, we have

$$\left. \begin{aligned} [\zeta_1, \zeta_1] = 0, \quad [\zeta_1, \zeta_2] = 0, \quad [\zeta_1, \zeta_3] = \zeta_1, \\ [\zeta_2, \zeta_1] = 0, \quad [\zeta_2, \zeta_2] = 0, \quad [\zeta_2, \zeta_3] = \zeta_2, \\ [\zeta_3, \zeta_1] = -\zeta_1, \quad [\zeta_3, \zeta_2] = -\zeta_2, \quad [\zeta_3, \zeta_3] = 0. \end{aligned} \right\} \quad (8.4)$$

Now using equation (2.3), we have

$$g(\mathcal{K}_1, \mathcal{K}_2) = \mathcal{K}_1^1\mathcal{K}_2^1 + \mathcal{K}_1^2\mathcal{K}_2^2 + \mathcal{K}_1^3\mathcal{K}_2^3. \quad (8.5)$$

Let us consider  $\nabla$ , a Levi-Civita connection admitting a Riemannian metric  $g$ . Using the Koszul formula

$$\begin{aligned} 2g(\nabla_{\mathcal{K}_1}\mathcal{K}_2, \mathcal{K}_3) &= \mathcal{K}_1g(\mathcal{K}_2, \mathcal{K}_3) + \mathcal{K}_2g(\mathcal{K}_3, \mathcal{K}_1) - \mathcal{K}_3g(\mathcal{K}_1, \mathcal{K}_2) \\ &\quad + g([\mathcal{K}_1, \mathcal{K}_2], \mathcal{K}_3) - g([\mathcal{K}_2, \mathcal{K}_3], \mathcal{K}_1) + g([\mathcal{K}_3, \mathcal{K}_1], \mathcal{K}_2). \end{aligned} \quad (8.6)$$

By virtue of (8.6), we have

$$\left. \begin{aligned} \nabla_{\zeta_1}\zeta_1 = 0, \quad \nabla_{\zeta_1}\zeta_2 = 0, \quad \nabla_{\zeta_1}\zeta_3 = \zeta_1, \\ \nabla_{\zeta_2}\zeta_1 = 0, \quad \nabla_{\zeta_2}\zeta_2 = -\zeta_3, \quad \nabla_{\zeta_2}\zeta_3 = \zeta_2, \\ \nabla_{\zeta_3}\zeta_1 = 0, \quad \nabla_{\zeta_3}\zeta_2 = 0, \quad \nabla_{\zeta_3}\zeta_3 = 0. \end{aligned} \right\} \quad (8.7)$$

Again for  $\mathcal{K}_1 = \mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2 + \mathcal{K}_1^3\zeta_3$  and  $\xi = \zeta_3$ , we have

$$\frac{3}{2}\nabla_{\mathcal{K}_1}\xi = \frac{3}{2}[\mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2], \quad (8.8)$$

i.e.

$$\nabla_{\mathcal{K}_1}\xi = \mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2, \quad (8.9)$$

$$\mathcal{K}_1 - \eta(\mathcal{K}_1)\xi = \mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2, \quad (8.10)$$

where  $\mathcal{K}_1^1, \mathcal{K}_1^2, \mathcal{K}_1^3$  are scalars. From equations (8.9) and (8.10) it follows that the manifold satisfies equation (2.5) for  $\xi = \zeta_3$ . Thus manifold is a Kenmotsu manifold. In reference of

equations (2.1), (3.1) and (8.7), we have the following:

$$\left. \begin{aligned} \tilde{\nabla}_{\zeta_1}\zeta_1 &= 0, & \tilde{\nabla}_{\zeta_1}\zeta_2 &= 0, & \tilde{\nabla}_{\zeta_1}\zeta_3 &= \frac{3}{2}\zeta_1 \\ \tilde{\nabla}_{\zeta_2}\zeta_1 &= 0, & \tilde{\nabla}_{\zeta_2}\zeta_2 &= 0, & \tilde{\nabla}_{\zeta_2}\zeta_3 &= \frac{3}{2}\zeta_2 \\ \tilde{\nabla}_{\zeta_3}\zeta_1 &= -\frac{\zeta_1}{2}, & \tilde{\nabla}_{\zeta_3}\zeta_2 &= -\frac{1}{2}\zeta_2, & \tilde{\nabla}_{\zeta_3}\zeta_3 &= 0. \end{aligned} \right\} \quad (8.11)$$

In equations (3.2) and (3.3), we have

$$\begin{aligned} \tilde{\mathcal{T}}(\zeta_1, \zeta_3) &= \eta(\zeta_3)\zeta_1 - \eta(\zeta_1)\zeta_3 \\ &= g(\zeta_3, \zeta_3)\zeta_1 - g(\zeta_1, \zeta_3)\zeta_3 \\ &= \zeta_1 \neq 0 \end{aligned} \quad (8.12)$$

and

$$\begin{aligned} (\tilde{\nabla}_{\zeta_1}g)(\zeta_1, \zeta_3) &= \frac{1}{2}\{2\eta(\zeta_1)g(\zeta_1, \zeta_3) - \eta(\zeta_1)g(\zeta_1, \zeta_3) - \eta(\zeta_3)g(\zeta_1, \zeta_1)\} \\ &= -\frac{1}{2} \neq 0. \end{aligned} \quad (8.13)$$

Thus it is clear from (3.1) that  $\tilde{\nabla}$  is a semi-symmetric non-metric connection. Now

$$\begin{aligned} \tilde{\nabla}_{\mathcal{K}_1}\xi &= \tilde{\nabla}_{\mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2 + \mathcal{K}_1^3\zeta_3} \\ &= \mathcal{K}_1^1\tilde{\nabla}_{\zeta_1}\zeta_3 + \mathcal{K}_1^2\tilde{\nabla}_{\zeta_2}\zeta_3 + \mathcal{K}_1^3\tilde{\nabla}_{\zeta_3}\zeta_3 \\ &= \frac{3}{2}(\mathcal{K}_1^1\zeta_1 + \mathcal{K}_1^2\zeta_2). \end{aligned} \quad (8.14)$$

By virtue of (8.8) and 8.12, we have verified the equations (3.6) and (3.7). The  $\mathfrak{R}(\zeta_i, \zeta_j)\zeta_k$ ;  $i, j, k = 1, 2, 3$  of connection  $\nabla$  can be estimated by using (3.11), (8.4) and (8.7), we have

$$\left. \begin{aligned} \mathfrak{R}(\zeta_1, \zeta_2)\zeta_1 &= 0, & \mathfrak{R}(\zeta_1, \zeta_2)\zeta_2 &= 0, & \mathfrak{R}(\zeta_1, \zeta_2)\zeta_3 &= 0, \\ \mathfrak{R}(\zeta_1, \zeta_3)\zeta_1 &= 0, & \mathfrak{R}(\zeta_1, \zeta_3)\zeta_2 &= 0, & \mathfrak{R}(\zeta_1, \zeta_3)\zeta_3 &= -\zeta_1, \\ \mathfrak{R}(\zeta_2, \zeta_3)\zeta_1 &= 0, & \mathfrak{R}(\zeta_2, \zeta_3)\zeta_2 &= 0, & \mathfrak{R}(\zeta_2, \zeta_3)\zeta_3 &= -\zeta_2, \end{aligned} \right\} \quad (8.15)$$

along with  $\mathfrak{R}(\zeta_i, \zeta_i)\zeta_i = 0$ ;  $\forall i = 1, 2, 3$ . By above discussions it has been verified equations (2.7), (2.8), (2.10) and (2.12) hold.

Analogously, we can estimate the  $\tilde{\mathfrak{R}}(\zeta_i, \zeta_j)\zeta_k$ ;  $i, j, k = 1, 2, 3$  of connection  $\tilde{\nabla}$  by using equations (3.10), (8.4) and (8.11), we have

$$\left. \begin{aligned} \tilde{\mathfrak{R}}(\zeta_1, \zeta_2)\zeta_1 &= 0, & \tilde{\mathfrak{R}}(\zeta_1, \zeta_2)\zeta_2 &= 0, & \tilde{\mathfrak{R}}(\zeta_1, \zeta_2)\zeta_3 &= 0, \\ \tilde{\mathfrak{R}}(\zeta_1, \zeta_3)\zeta_1 &= 0, & \tilde{\mathfrak{R}}(\zeta_1, \zeta_3)\zeta_2 &= 0, & \tilde{\mathfrak{R}}(\zeta_1, \zeta_3)\zeta_3 &= -\frac{3}{4}\zeta_1, \\ \tilde{\mathfrak{R}}(\zeta_2, \zeta_3)\zeta_1 &= 0, & \tilde{\mathfrak{R}}(\zeta_2, \zeta_3)\zeta_2 &= 0, & \tilde{\mathfrak{R}}(\zeta_2, \zeta_3)\zeta_3 &= -\frac{3}{4}\zeta_2, \end{aligned} \right\} \quad (8.16)$$

along with  $\tilde{\mathfrak{R}}(\zeta_i, \zeta_i)\zeta_i = 0$ ;  $\forall i = 1, 2, 3$ .

By virtue of (8.15) and (8.16), we have verified equations (4.1), (4.5), (4.6), (4.7) and (4.8). The Ricci tensors  $\mathcal{S}(\zeta_j, \zeta_k)$ ;  $j, k = 1, 2, 3$  of connection  $\nabla$  can be estimated by using (8.15) as under

$$\mathcal{S}(\zeta_j, \zeta_k) = \sum_{i=1}^3 g(\mathfrak{R}(\zeta_i, \zeta_j)\zeta_k, \zeta_i).$$

It is as under:

$$\left. \begin{aligned} \mathcal{S}(\zeta_1, \zeta_1) = 0, \quad \mathcal{S}(\zeta_2, \zeta_2) = 0, \quad \mathcal{S}(\zeta_3, \zeta_3) = -2, \\ \mathcal{S}(\zeta_1, \zeta_2) = 0, \quad \mathcal{S}(\zeta_1, \zeta_3) = 0, \quad \mathcal{S}(\zeta_2, \zeta_3) = 0. \end{aligned} \right\} \quad (8.17)$$

In view of equation (8.17), we can easily verify equation (2.12).

Also in view of equation (8.17) we have verified the following:

$$\left. \begin{aligned} (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_1, \phi \zeta_2) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_2, \phi \zeta_3) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_1, \phi \zeta_1) = 0, \\ (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_1, \phi \zeta_3) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_3, \phi \zeta_1) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_2, \phi \zeta_2) = 0, \\ (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_2, \phi \zeta_1) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_3, \phi \zeta_2) = 0, \quad (\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \zeta_3, \phi \zeta_3) = 0. \end{aligned} \right\} \quad (8.18)$$

Thus we note that

$$(\nabla_{\mathcal{K}_1} \mathcal{S})(\phi \mathcal{K}_2, \phi \mathcal{K}_3) = 0. \quad (8.19)$$

$\forall \mathcal{K}_1, \mathcal{K}_2, \mathcal{K}_3 \in \mathfrak{X}(\mathcal{M})$ . Hence the Ricci tensor is  $\eta$ -parallel. In view of equation (8.18) we can easily verify the equation (2.16).

The  $\tilde{\mathcal{S}}(\zeta_j, \zeta_k); j, k = 1, 2, 3$  of  $\tilde{\nabla}$  estimated by using (8.16) as under

$$\tilde{\mathcal{S}}(\zeta_j, \zeta_k) = \sum_{i=1}^3 g(\tilde{\mathcal{R}}(\zeta_i, \zeta_j)\zeta_k, \zeta_i).$$

It follows as under:

$$\left. \begin{aligned} \tilde{\mathcal{S}}(\zeta_1, \zeta_1) = 0, \quad \tilde{\mathcal{S}}(\zeta_2, \zeta_2) = 0, \quad \tilde{\mathcal{S}}(\zeta_3, \zeta_3) = -\frac{3}{2}, \\ \tilde{\mathcal{S}}(\zeta_1, \zeta_2) = 0, \quad \tilde{\mathcal{S}}(\zeta_1, \zeta_3) = 0, \quad \tilde{\mathcal{S}}(\zeta_2, \zeta_3) = 0. \end{aligned} \right\} \quad (8.20)$$

In view of equation (8.20), we can say that the example validate the equations (4.2) and (4.9).

Hence, we can say that given example is suitable for verification.

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## Competing Interests

The authors declare that they have no competing interests.

## Authors' Contributions

All the authors contributed significantly in writing this article. The authors read and approved the final manuscript.

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