



η -Einstein (k, μ) -Space Forms

Research Article

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Abstract. In this paper we obtain the scalar curvatures of a (k, μ) -space form under h -projective, ϕ -projective semi symmetric and h -Weyl and ϕ -Weyl semisymmetry conditions.

Keywords. (k, μ) -space form; h -projective; ϕ -projective semi symmetric; h -Weyl; ϕ -Weyl semi symmetry

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1. Introduction

A class of (k, μ) contact metric manifolds [3] is of interest as it contains both the classes of Sasakian and non-Sasakian cases. The contact metric manifolds for which the characteristic vector field ξ belongs to (k, μ) -nullity distribution for some real numbers k and μ are called (k, μ) contact metric manifolds. A full classification of (k, μ) -contact metric manifolds was given by Boeckx [4] and many authors [2] studied (k, μ) -contact metric manifolds. T. Koufogiorgos proved in [1] that if a (k, μ) -space M has constant ϕ -sectional curvature c and dimension greater than 3, the curvature tensor of this (k, μ) -space form is given by

$$\begin{aligned}
 4R(X, Y)Z = & [(c + 3)\{g(Y, Z)X - g(X, Z)Y\} + (c + 3 - 4k)\{\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X \\
 & + g(X, Z)\eta(Y)\xi - g(Y, Z)\eta(X)\xi\} + (c - 1)\{2g(X, \phi Y)\phi Z + g(X, \phi Z)\phi Y \\
 & - g(Y, \phi Z)\phi X\} - 2\{g(hX, Z)hY - g(hY, Z)hX + 2g(X, Z)hY - 2g(Y, Z)hX \\
 & - 2\eta(X)\eta(Z)hY + 2\eta(Y)\eta(Z)hX + 2g(hX, Z)Y - 2g(hY, Z)X \\
 & + 2g(hY, Z)\eta(X)\xi - 2g(hX, Z)\eta(Y)\xi - g(\phi hX, Z)\phi hY + g(\phi hY, Z)\phi hX\} \\
 & + 4\mu\{\eta(Y)\eta(Z)hX - \eta(X)\eta(Z)hY + g(hY, Z)\eta(X)\xi - g(hX, Z)\eta(Y)\xi\}], \quad (1.1)
 \end{aligned}$$

for any vector fields X, Y, Z , where $2h = L_\xi\phi$ and L is the usual Lie derivative.

The projective curvature tensor is an important tensor from the differential geometric point of view. An $(2n + 1)$ -dimensional Riemannian manifold M is locally projectively flat if there exists a one-to-one correspondence between each coordinate neighbourhood of M and a domain in Euclidean space such that any geodesic of the Riemannian manifold corresponds to a straight line in Euclidean space. It is well-known that for $n \geq 1$, M is locally projectively flat if and only if the projective curvature tensor P vanishes. Here P is defined by

$$P(X, Y)Z = R(X, Y)Z - \frac{1}{2n}[S(Y, Z)X - S(X, Z)Y], \quad (1.2)$$

where S is the Ricci tensor of M .

In an $(2n + 1)$ -dimensional Riemannian manifold, the conformal curvature tensor C is given by

$$C(X, Y)Z = R(X, Y)Z - \frac{1}{2n-1}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] + \frac{r}{2n(2n-1)}[g(Y, Z)X - g(X, Z)Y], \quad (1.3)$$

where r is a scalar curvature and Q is the Ricci operator defined by $g(QX, Y) = S(X, Y)$.

The paper is organised as follows. In Section 2 we give some preliminary results of (k, μ) -space forms. Section 3 deals with h -projective and ϕ -projective semi-symmetric non-Sasakian (k, μ) -space forms. Section 4 is devoted to the study of h -Weyl and ϕ -Weyl semi-symmetric non-Sasakian (k, μ) -space forms. In all the cases the manifold becomes an η -Einstein manifold and we obtain scalar curvatures of (k, μ) -space forms.

2. Preliminaries

A $(2n + 1)$ -dimensional differential manifold M is said to admit an almost contact metric structure (ϕ, ξ, η, g) if it satisfies the following relations

$$\phi^2 X = -X + \eta(X)\xi, \quad \phi\xi = 0, \quad (2.1)$$

$$\eta(\xi) = 1, g(X, \xi) = \eta(X), \quad \eta(\phi X) = 0, \quad (2.2)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (2.3)$$

$$g(\phi X, Y) = -g(X, \phi Y), \quad g(\phi X, X) = 0, \quad (2.4)$$

$$(\nabla_X \eta)Y = g(\nabla_X \xi, Y), \quad (2.5)$$

$$g(X, \phi Y) = d\eta(X, Y), \quad (2.6)$$

for all vector fields X, Y on M . In a contact metric manifold the $(1, 1)$ tensor field h defined by $h = \frac{1}{2}L_\xi\phi$, where L denotes the Lie differentiation, is a symmetric operator anti-commutative with ϕ and satisfies $h\xi = 0$, $h\phi = -\phi h$, $Tr h = Tr \phi h = 0$. Moreover in any contact metric manifold, we have $\nabla_X \xi = -\phi X - \phi hX$. In [3] Blair et al. introduced a class of contact metric manifold M which satisfy

$$R(X, Y)\xi = k\{\eta(Y)X - \eta(X)Y\} + \mu\{\eta(Y)hX - \eta(X)hY\}, \quad (2.7)$$

where k and μ are real constants. This class of contact metric manifolds are called (k, μ) manifolds.

Also in a (k, μ) -contact metric manifold, the following relations hold ([3], [4]):

$$h^2 = (k - 1)\phi^2, k \leq 1, \tag{2.8}$$

$$S(X, Y) = \frac{1}{4} \left[(c(2n + 1) + 6n + 4k - 5)g(X, Y) - (c(2n + 1) + 6n + 4k - 5 - 8nk)\eta(X)\eta(Y) + (8 - 8n + 4\mu)g(Y, hX) \right], \tag{2.9}$$

$$r = \frac{n}{2} [c(2n + 1) + 6n + 4k - 5] + 2nk, \tag{2.10}$$

$$S(X, \xi) = 8nk\eta(X), S(\xi, \xi) = 8nk,$$

where S is the Ricci tensor of the type $(0, 2)$ and r is the scalar curvature of the manifold.

If $\mu = 0$, the (k, μ) -nullity distribution $N(k, \mu)$ is reduced to the k -nullity distribution [5], where k -nullity distribution $N(k)$ of a Riemannian manifold M is defined by

$$N(k) : p \rightarrow N_p(k) = \{W \in T_p(M) / R(X, Y)W = k(g(Y, W)X - g(X, W)Y)\}.$$

If $\xi \in N(k)$, then we call M a $N(k)$ -contact metric manifold.

The class of (k, μ) -contact metric manifolds contain both the class of Sasakian ($k = 1$ and $h = 0$) and non-Sasakian ($k \neq 1$ and $h \neq 0$) manifolds. Throughout the paper we denote by M^{2n+1} , a $(2n + 1)$ -dimensional non-Sasakian (k, μ) -space form. A contact metric manifold is said to be η -Einstein if $Q = aId + b\eta \otimes \xi$, where a, b are smooth functions on M^{2n+1} .

3. h -Projectively and ϕ -Projectively Semi Symmetric Non-Sasakian (k, μ) -Space Form

Definition 3.1. A (k, μ) -space form M is said to be h -projectively semi-symmetric if $P(X, Y) \cdot h = 0$ holds in M .

We now prove the following theorem.

Theorem 3.1. Let M be a non-Sasakian (k, μ) -space form. If M is h -projectively semi-symmetric, then M is an η -Einstein manifold.

Proof. Let M be an $(2n + 1)$ -dimensional h -projectively semi symmetric non-Sasakian (k, μ) -space form. The condition $P(X, Y) \cdot h = 0$ turns into

$$(P(X, Y) \cdot h)Z = P(X, Y)hZ - hP(X, Y)Z = 0. \tag{3.1}$$

From (1.1), we have

$$\begin{aligned} &R(X, Y)hZ - hR(X, Y)Z \\ &= \frac{1}{4} [(c + 3)\{g(Y, hZ)X - g(X, hZ)Y - g(Y, Z)hX + g(X, Z)hY\} \\ &\quad + (c + 3 - 4k)\{g(X, hZ)\eta(Y)\xi - g(Y, hZ)\eta(X)\xi - \eta(X)\eta(Z)hY \\ &\quad + \eta(Y)\eta(Z)hX\} + (c - 1)\{g(X, \phi hZ)\phi Y - g(Y, \phi hZ)\phi X \\ &\quad - g(X, \phi Z)h\phi Y + g(Y, \phi Z)h\phi X\} - 2\{g(hX, hZ)hY - g(hY, hZ)hX \end{aligned}$$

$$\begin{aligned}
& + 2g(X, hZ)hY - 2g(Y, hZ)hX + 2g(hX, hZ)Y - 2g(hY, hZ)X \\
& + 2g(hY, hZ)\eta(X)\xi - 2g(hX, hZ)\eta(Y)\xi - g(\phi hX, hZ)\phi hY \\
& + g(\phi hY, hZ)\phi hX + g(hX, Z)h^2Y - g(hY, Z)h^2X + 2g(X, Z)h^2Y \\
& - 2g(Y, Z)h^2X - 2\eta(X)\eta(Z)h^2Y + 2\eta(Y)\eta(Z)h^2X - g(\phi hX, Z)h\phi hY \\
& + g(\phi hY, Z)h\phi hX + 2g(hX, Z)hY - 2g(hY, Z)hX + 4\mu\{g(hY, hZ)\eta(X)\xi \\
& - g(hX, hZ)\eta(Y)\xi + \eta(X)\eta(Z)h^2Y - \eta(Y)\eta(Z)h^2X\}. \tag{3.2}
\end{aligned}$$

for any vector fields X, Y, Z . Using (1.3), (3.1) and (3.2), we have

$$\begin{aligned}
& \frac{1}{4}[(c+3)\{g(Y, hZ)X - g(X, hZ)Y - g(Y, Z)hX + g(X, Z)hY\} \\
& + (c+3-4k)\{g(X, hZ)\eta(Y)\xi - g(Y, hZ)\eta(X)\xi - \eta(X)\eta(Z)hY \\
& + \eta(Y)\eta(Z)hX\} + (c-1)\{g(X, \phi hZ)\phi Y - g(Y, \phi hZ)\phi X - g(X, \phi Z)h\phi Y \\
& + g(Y, \phi Z)h\phi X\} - 2\{g(hX, hZ)hY - g(hY, hZ)hX + 2g(X, hZ)hY \\
& - 2g(Y, hZ)hX + 2g(hX, hZ)Y - 2g(hY, hZ)X + 2g(hY, hZ)\eta(X)\xi \\
& - 2g(hX, hZ)\eta(Y)\xi g(\phi hX, hZ)\phi hY + g(\phi hY, hZ)\phi hX + g(hX, Z)h^2Y \\
& - g(hY, Z)h^2X + 2g(X, Z)h^2Y - 2g(Y, Z)h^2X - 2\eta(X)\eta(Z)h^2Y + 2\eta(Y)\eta(Z)h^2X \\
& - g(\phi hX, Z)h\phi hY + g(\phi hY, Z)h\phi hX + 2g(hX, Z)hY - 2g(hY, Z)hX\} \\
& + 4\mu\{g(hY, hZ)\eta(X)\xi - g(hX, hZ)\eta(Y)\xi + \eta(X)\eta(Z)h^2Y - \eta(Y)\eta(Z)h^2X\}] \\
& - \frac{1}{2n}[S(Y, hZ)X - S(X, hZ)Y - S(Y, Z)hX + S(X, Z)hY] = 0. \tag{3.3}
\end{aligned}$$

Replacing X by hX and contracting with W , by using (2.8) and symmetry property of h , we get

$$\begin{aligned}
& \frac{1}{4}[(c+3)\{g(Y, hZ)g(hX, W) - g(hX, hZ)g(Y, W) + (k-1)g(Y, Z)g(X, W) \\
& - (k-1)g(Y, Z)\eta(X)\eta(W) + g(hX, Z)g(hY, W)\} + (c+3-4k)\{g(hX, hZ)\eta(Y)\eta(W) \\
& - (k-1)\eta(Y)\eta(Z)g(X, W) + (k-1)\eta(X)\eta(Z)\eta(Y)\eta(W)\} + (c-1)\{g(hX, \phi hZ)g(\phi Y, W) \\
& - g(Y, \phi hZ)g(\phi hX, W) - g(hX, \phi Z)g(h\phi Y, W) + (k-1)g(Y, \phi Z)g(\phi X, W)\} \\
& - 2\{-(k-1)g(X, hZ)g(hY, W) + (k-1)[g(hY, hZ)g(X, W) - g(hY, hZ)\eta(X)\eta(W) \\
& + 2g(hX, hZ)g(hY, W) + 2(k-1)[g(Y, hZ)g(X, W) - g(Y, hZ)\eta(X)\eta(W)] \\
& - 2(k-1)g(X, hZ)g(Y, W) - 2g(hY, hZ)g(hX, W) + 2(k-1)g(X, hZ)\eta(Y)\eta(W) \\
& + (k-1)g(\phi X, hZ)g(\phi hY, W) - (k-1)g(\phi hY, hZ)g(\phi X, W) + (k-1)^2[g(X, Z)g(Y, W) \\
& + 2(k-1)[-g(hX, Z)g(Y, W) + g(hX, Z)\eta(Y)\eta(W)] + 2(k-1)g(Y, Z)g(hX, W) \\
& - 2(k-1)\eta(Y)\eta(Z)g(hX, W) + (k-1)^2g(\phi X, Z)g(\phi Y, W) + (k-1)g(\phi hY, Z)g(\phi hX, W) \\
& + 2(k-1)[-g(X, Z)g(hY, W) + \eta(X)\eta(Z)g(hY, W)] + 2(k-1)[g(hY, Z)g(X, W) \\
& - g(hY, Z)\eta(X)\eta(W)] + 4\mu\{(k-1)g(X, hZ)\eta(Y)\eta(W) + (k-1)\eta(Y)\eta(Z)g(hX, W)\} \\
& - \frac{1}{2n}[S(Y, Z)g(hX, W) - S(hX, hZ)g(Y, W) + (k-1)[S(Y, Z)g(X, W) \\
& - S(Y, Z)\eta(X)\eta(W)] + S(hX, Z)g(hY, W)] = 0. \tag{3.4}
\end{aligned}$$

Let $e_i, i = 1, 2, 3, \dots, 2n + 1$ be an orthonormal basis of vector fields in M . If we put $X = W = e_i$ in (3.4) and summing over i , then using (2.9), we obtain

$$\begin{aligned} & \frac{1}{4} [(c+3)(k-1)2n + 2(c-1)(k-1) - 2(k-1)^2]g(Y, Z) \\ & + [-(c+3-4k)2n(k-1) - 2(c-1)(k-1) + 2(k-1)^2]\eta(Y)\eta(Z) \\ & + [(k-1)(-8+10n)]g(Y, hZ) - (k-1)S(Y, Z) = 0. \end{aligned} \quad (3.5)$$

Again using (2.9) in (3.5), we obtain

$$g(Y, hZ) = \left[\frac{6k-c-5}{18n-4\mu-16} \right] g(Y, Z) + \left[\frac{c-6k+5}{18n-4\mu-16} \right] \eta(Y)\eta(Z). \quad (3.6)$$

In view of (3.6), (3.5) takes the form

$$S(Y, Z) = A_1g(Y, Z) + B_1\eta(Y)\eta(Z), \quad (3.7)$$

where

$$\begin{aligned} A_1 &= 2n(c+3) + 2(c-1) - 2(k-1) + \frac{(8-10n)(c-6k+5)}{-16+18n-4\mu}, \\ B_1 &= -2n(c+3-4k) - 2(c-1) + 2(k-1) + \frac{(-8+10n)(c-6k+5)}{-16+18n-4\mu}. \end{aligned}$$

Thus M is an η -Einstein manifold.

Taking $Y = Z = e_i$ in (3.7), we obtain

$$r = n\{(n+1)c + 3n + k\}. \quad (3.8)$$

A h -projectively semi-symmetric non-Sasakian (k, μ) -space form is an η -Einstein manifold and the scalar curvature in this case is $r = n\{(n+1)c + 3n + k\}$.

Comparing r of (3.8) with (2.10), we get $c = 6k - 5$. \square

Definition 3.2. A (k, μ) -space form M is said to be ϕ -projectively semi-symmetric if $P(X, Y) \cdot \phi = 0$ holds in M .

Theorem 3.2. Let M be a non-Sasakian (k, μ) -space form-space form. If M is ϕ -projectively semi symmetric, then M is an η -Einstein manifold.

Proof. Let M be an $(2n + 1)$ -dimensional ϕ -projectively semi-symmetric non-Sasakian (k, μ) -space form-space form. The condition $P(X, Y) \cdot \phi = 0$ turns into

$$(P(X, Y) \cdot \phi)Z = P(X, Y)\phi Z - \phi P(X, Y)Z = 0. \quad (3.9)$$

From (1.1), we have

$$\begin{aligned} & R(X, Y)\phi Z - \phi R(X, Y)Z \\ &= \frac{1}{4} [(c+3)\{g(Y, \phi Z)X - g(X, \phi Z)Y - g(Y, Z)\phi X + g(X, Z)\phi Y\} \\ &+ (c+3-4k)\{g(X, \phi Z)\eta(Y)\xi - g(Y, \phi Z)\eta(X)\xi - \eta(X)\eta(Z)\phi Y \\ &+ \eta(Y)\eta(Z)\phi X\} + (c-1)\{g(X, \phi^2 Z)\phi Y - g(Y, \phi^2 Z)\phi X - g(X, \phi Z)\phi^2 Y \end{aligned}$$

$$\begin{aligned}
& + g(Y, \phi Z)\phi^2 X - 2\{g(hX, \phi Z)hY - g(hY, \phi Z)hX + 2g(X, \phi Z)hY \\
& - 2g(Y, \phi Z)hX + 2g(hX, \phi Z)Y - 2g(hY, \phi Z)X + 2g(hY, \phi Z)\eta(X)\xi \\
& - 2g(hX, \phi Z)\eta(Y)\xi - g(\phi hX, \phi Z)\phi hY + g(\phi hY, \phi Z)\phi hX \\
& + g(hX, Z)\phi hY - g(hY, Z)\phi hX + 2g(X, Z)\phi hY - 2g(Y, Z)\phi hX \\
& - 2\eta(X)\eta(Z)\phi hY + 2\eta(Y)\eta(Z)\phi hX - g(\phi hX, Z)\phi^2 hY g(\phi hY, Z)\phi^2 hX \\
& + 2g(hX, Z)\phi Y - 2g(hY, Z)\phi X\} + 4\mu\{g(hY, \phi Z)\eta(X)\xi \\
& - g(hX, \phi Z)\eta(Y)\xi + \eta(X)\eta(Z)\phi hY - \eta(Y)\eta(Z)\phi hX\}. \tag{3.10}
\end{aligned}$$

for any vector fields X, Y, Z . Using (1.3) and (3.9) in (3.10), we have

$$\begin{aligned}
& \frac{1}{4}[(c+3)\{g(Y, \phi Z)X - g(X, \phi Z)Y - g(Y, Z)\phi X + g(X, Z)\phi Y\} \\
& + (c+3-4k)\{g(X, \phi Z)\eta(Y)\xi - g(Y, \phi Z)\eta(X)\xi - \eta(X)\eta(Z)\phi Y + \eta(Y)\eta(Z)\phi X\} \\
& + (c-1)\{-g(X, Z)\phi Y + \eta(Z)\eta(X)\phi Y + g(Y, Z)\phi X - \eta(Z)\eta(Y)\phi X + g(X, \phi Z)\phi Y \\
& - g(X, \phi Z)\eta(Y)\xi - g(Y, \phi Z)X + g(Y, \phi Z)\eta(X)\xi\} - 2\{g(hX, \phi Z)hY - g(hY, \phi Z)hX \\
& + 2g(X, \phi Z)hY - 2g(Y, \phi Z)hX + 2g(hX, \phi Z)Y - 2g(hY, \phi Z)X + 2g(hY, \phi Z)\eta(X)\xi \\
& - 2g(hX, \phi Z)\eta(Y)\xi - g(\phi hX, \phi Z)\phi hY + g(\phi hY, \phi Z)\phi hX + g(hX, Z)\phi hY - g(hY, Z)\phi hX \\
& + 2g(X, Z)\phi hY - 2g(Y, Z)\phi hX - 2\eta(X)\eta(Z)\phi hY + 2\eta(Y)\eta(Z)\phi hX \\
& - g(\phi hX, Z)\phi^2 hY + g(\phi hY, Z)\phi^2 hX + 2g(hX, Z)\phi Y - 2g(hY, Z)\phi X\} \\
& + 4\mu\{g(hY, \phi Z)\eta(X)\xi - g(hX, \phi Z)\eta(Y)\xi + \eta(X)\eta(Z)\phi hY - \eta(Y)\eta(Z)\phi hX\}] \\
& - \frac{1}{2n}[S(Y, \phi Z)X - S(X, \phi Z)Y - S(Y, Z)\phi X + S(X, Z)\phi Y] = 0. \tag{3.11}
\end{aligned}$$

Replacing X by ϕX and contracting with W in (3.11) from (2.4), we obtain

$$\begin{aligned}
& \frac{1}{4}[(c+3)\{g(Y, \phi Z)g(\phi X, W) - g(\phi X, \phi Z)g(Y, W) + g(Y, Z)g(X, W) - g(Y, Z)\eta(X)\eta(W) \\
& + g(\phi X, Z)g(\phi Y, W)\} + (c+3-4k)\{g(\phi X, \phi Z)\eta(Y)\eta(W) - \eta(Y)\eta(Z)g(X, W) \\
& + \eta(Y)\eta(Z)\eta(X)\eta(W)\} + (c-1)\{-g(\phi X, Z)g(\phi Y, W) - g(Y, Z)g(X, W) + g(Y, Z)\eta(X)\eta(W) \\
& + \eta(Z)\eta(Y)g(X, W) + g(X, Z)g(Y, W) - \eta(Z)\eta(X)g(Y, W) - g(X, Z)\eta(Y)\eta(W) \\
& - g(Y, \phi Z)g(\phi X, W)\} - 2\{-g(X, Z)g(hY, W) - g(hY, \phi Z)g(h\phi X, W) + 2[-g(X, Z)g(hY, W) \\
& + \eta(Z)\eta(X)g(hY, W)] - 2g(Y, \phi Z)g(h\phi X, W) - 2g(hX, Z)g(Y, W) - 2g(hY, \phi Z)g(\phi X, W) \\
& + 2g(hX, Z)\eta(Y)\eta(W) - g(h\phi X, Z)g(h\phi Y, W) + g(hY, Z)g(hX, W) + g(h\phi X, Z)g(\phi hY, W) \\
& - g(hY, Z)g(hX, W) + 2g(\phi X, Z)g(\phi hY, W) - 2g(Y, Z)g(hX, W) + 2\eta(Y)\eta(Z)g(hX, W) \\
& - g(\phi hY, Z)g(h\phi X, W)\} + 4\mu\{g(hX, Z)\eta(Y)\eta(W) - \eta(Y)\eta(Z)g(hX, W)\}] \\
& - \frac{1}{2n}[S(Y, \phi Z)g(\phi X, W) - S(\phi X, \phi Z)g(Y, W) + S(Y, Z)g(X, W) - S(Y, Z)\eta(X)\eta(W) \\
& - \frac{1}{2n}[S(Y, \phi Z)g(\phi X, W) - S(\phi X, \phi Z)g(Y, W) + S(Y, Z)g(X, W) - S(Y, Z)\eta(X)\eta(W) \\
& + S(\phi X, Z)g(\phi Y, W)] = 0. \tag{3.12}
\end{aligned}$$

Let $\{e_i\}$, $i = 1, 2, \dots, 2n + 1$ be an orthonormal basis of vector fields in M . If we put $X = W = e_i$ in (3.11) and summing over i , then using (2.2) and (2.8), we obtain

$$\begin{aligned} & \frac{1}{4} \left[\left[8n + 6k - 14 + \frac{c(2n + 1) + 6n + 4k - 5}{n} \right] g(Y, Z) \right. \\ & \quad + \left[c + 8nk - 2n - 2k - 6 - \frac{c(2n + 1) + 6n + 4k - 5}{n} \right] \eta(Y)\eta(Z) \\ & \quad \left. + 18g(Z, hY) \right] - S(Y, Z) = 0. \end{aligned} \quad (3.13)$$

Using (2.9) in (3.13), we obtain

$$S(Y, Z) = A_2 g(Y, Z) + B_2 \eta(Y)\eta(Z), \quad (3.14)$$

where

$$\begin{aligned} A_2 &= \left[\left(8n + 6k - 14 + \frac{c(2n + 1) + 6n + 4k - 5}{n} \right) (c - 17) \right] - (c(2n + 1) + 6n + 4k - 5), \\ B_2 &= \left[\left(c + 8nk - 2n - 2k - 6 - \frac{c(2n + 1) + 6n + 4k - 5}{n} \right) (c - 17) \right] - (c(2n + 1) + 6n + 4k - 5). \end{aligned}$$

Thus M is an η -Einstein manifold.

Taking $Y = Z = e_i$ in (3.13), we obtain

$$r = \frac{1}{4} [16n^2 + 20nk - 16n + 12k - 14 + 4nc + 2c]. \quad (3.15)$$

A ϕ -projectively semi symmetric non-Sasakian (k, μ) -space form is an η -Einstein manifold and the scalar curvature in this case is

$$r = \frac{1}{4} [16n^2 + 20nk - 16n + 12k - 14 + 4nc + 2c], \quad (3.16)$$

Comparing r of ϕ -projectively semi-symmetric non-Sasakian (k, μ) -contact metric space form with (2.10), we get

$$c = \frac{2n^2 + 2nk + 3n + 6k - 7}{2n^2 - n - 1}. \quad \square$$

4. h -Weyl and ϕ -Weyl Semi-symmetric Non-Sasakian (k, μ) -Space Form

Definition 4.1. A (k, μ) -space form M is said to be h -Weyl semi-symmetric if $C(X, Y) \cdot h = 0$ holds on M .

Theorem 4.1. Let M be a non-Sasakian (k, μ) -space form-space form. If M is h -Weyl semi symmetric, then M is an η -Einstein manifold.

Proof. Let M be an $(2n + 1)$ -dimensional h -Weyl semi symmetric non-Sasakian (k, μ) -space form-space form. The condition $C(X, Y) \cdot h = 0$ turns into

$$(C(X, Y) \cdot h)Z = C(X, Y)hZ - hC(X, Y)Z = 0, \quad (4.1)$$

for any vector fields X, Y, Z . Using (1.3) and (3.1) in (4.1), we have

$$\begin{aligned} & \frac{1}{4}[(c+3)\{g(Y, hZ)X - g(X, hZ)Y - g(Y, Z)hX + g(X, Z)hY\} \\ & + (c+3-4k)\{g(X, hZ)\eta(Y)\xi - g(Y, hZ)\eta(X)\xi - \eta(X)\eta(Z)hY \\ & + \eta(Y)\eta(Z)hX\} + (c-1)\{g(X, \phi hZ)\phi Y - g(Y, \phi hZ)\phi X - g(X, \phi Z)h\phi Y \\ & + g(Y, \phi Z)h\phi X\} - 2\{g(hX, hZ)hY - g(hY, hZ)hX + 2g(X, hZ)hY \\ & - 2g(Y, hZ)hX + 2g(hX, hZ)Y - 2g(hY, hZ)X + 2g(hY, hZ)\eta(X)\xi \\ & - 2g(hX, hZ)\eta(Y)\xi - g(\phi hX, hZ)\phi hY + g(\phi hY, hZ)\phi hX + g(hX, Z)h^2Y \\ & - g(hY, Z)h^2X + 2g(X, Z)h^2Y - 2g(Y, Z)h^2X - 2\eta(X)\eta(Z)h^2Y \\ & + 2\eta(Y)\eta(Z)h^2X - g(\phi hX, Z)h\phi hY + g(\phi hY, Z)h\phi hX + 2g(hX, Z)hY \\ & - 2g(hY, Z)hX\} + 4\mu\{g(hY, hZ)\eta(X)\xi - g(hX, hZ)\eta(Y)\xi + \eta(X)\eta(Z)h^2Y \\ & + \frac{r}{2n(2n-1)}\{g(Y, hZ)X - g(X, hZ)Y - g(Y, Z)hX + g(X, Z)hY\} = 0. \end{aligned} \quad (4.2)$$

Replacing X by hX , contracting with W and using (4.2) and symmetry property of h , we obtain,

$$\begin{aligned} & \frac{1}{4}[(c+3)\{g(Y, hZ)g(hX, W) - g(hX, hZ)g(Y, W) + (k-1)g(Y, Z)g(X, W) \\ & - (k-1)g(Y, Z)\eta(X)\eta(W) + g(hX, Z)g(hY, W)\} + (c+3-4k)\{g(hX, hZ)\eta(Y)\eta(W) \\ & - (k-1)\eta(Y)\eta(Z)g(X, W) + (k-1)\eta(X)\eta(Z)\eta(Y)\eta(W)\} + (c-1)\{g(hX, \phi hZ)g(\phi Y, W) \\ & - g(Y, \phi hZ)g(\phi hX, W) - g(hX, \phi Z)g(h\phi Y, W) + (k-1)g(Y, \phi Z)g(\phi X, W)\} \\ & - 2\{-(k-1)g(X, hZ)g(hY, W) + (k-1)[g(hY, hZ)g(X, W) - g(hY, hZ)\eta(X)\eta(W)] \\ & + 2g(hX, hZ)g(hY, W) + 2(k-1)[g(Y, hZ)g(X, W) - g(Y, hZ)\eta(X)\eta(W)] \\ & - 2(k-1)g(X, hZ)g(Y, W) - 2g(hY, hZ)g(hX, W) + 2(k-1)g(X, hZ)\eta(Y)\eta(W) \\ & + (k-1)g(\phi X, hZ)g(\phi hY, W) - (k-1)g(\phi hY, hZ)g(\phi X, W) + (k-1)^2[g(X, Z)g(Y, W) \\ & - g(X, Z)\eta(Y)\eta(W) - \eta(X)\eta(Z)g(Y, W) + \eta(X)\eta(Y)\eta(Z)\eta(W)] + (k-1)g(hY, Z)g(hX, W) \\ & + 2(k-1)[-g(hX, Z)g(Y, W) + g(hX, Z)\eta(Y)\eta(W)] + 2(k-1)g(Y, Z)g(hX, W) \\ & - g(hY, Z)\eta(X)\eta(W)\} + 4\mu\{(k-1)g(X, hZ)\eta(Y)\eta(W) + (k-1)\eta(Y)\eta(Z)g(hX, W)\} \\ & - \frac{1}{2n-1}[S(Y, hZ)g(hX, W) + (k-1)[S(X, Z)g(Y, W) - 2nk\eta(Z)\eta(X)g(Y, W)] \\ & + g(Y, hZ)g(QhX, W) + g(X, Z)g(QY, W) - \eta(Z)\eta(X)g(QY, W) + (k-1)[S(Y, Z)g(X, W) \\ & - S(Y, Z)\eta(X)\eta(W)] + S(hX, Z)g(hY, W) - g(Y, Z)g(hQhX, W) + g(Y, hZ)g(QhX, W) \\ & + g(X, Z)g(QY, W) - \eta(Z)\eta(X)g(QY, W) + (k-1)[S(Y, Z)g(X, W) - S(Y, Z)\eta(X)\eta(W)] \\ & + S(hX, Z)g(hY, W) - g(Y, Z)g(hQhX, W) + g(hX, Z)g(hQY, W)\} \\ & + \frac{r}{2n(2n-1)}\{g(Y, hZ)g(hX, W) + g(X, Z)g(Y, W) - \eta(X)\eta(Z)g(Y, W) \\ & + (k-1)[g(Y, Z)g(X, W) - g(Y, Z)\eta(X)\eta(W)] + g(hX, Z)g(hY, W)\} = 0. \end{aligned} \quad (4.3)$$

Taking $Y = W = \xi$ in (4.3), we obtain

$$S(X, Z) = \left[k(2n - 1) - \frac{2nk}{k - 1} + \frac{r}{2n(k - 1)} \right] g(X, Z) + \left[-k(2n - 1) + \frac{2nk^2}{k - 1} - \frac{r}{2n(k - 1)} \right] \eta(X)\eta(Z) + 4\mu(2n - 1)g(hX, Z) \tag{4.4}$$

Now using (2.9) in (4.4), we get

$$g(X, hZ) = \frac{1}{2 - 2n - 8n\mu + 5\mu} \left[\frac{8nk(2n - 1)(k - 1) - 4n^2k + r}{2n(k - 1)} - \frac{c(2n + 1) + 6n + 4k - 5}{4} \right] g(X, Z) + \left[\frac{-8nk(2n - 1)(k - 1) + 4n^2k^2 - r}{2n(k - 1)} + \frac{c(2n + 1) + 6n + 4k - 5 - 8nk}{4} \right] \eta(X)\eta(Z) \tag{4.5}$$

Using (4.5) in (4.4), we obtain

$$S(X, Z) = A'_1 g(X, Z) + B'_1 \eta(X)\eta(Z), \tag{4.6}$$

where

$$A'_1 = \frac{4\mu(2n - 1)}{2 - 2n - 8n\mu + 5\mu} \left[\frac{8nk(2n - 1)(k - 1) - 4n^2k + r}{2n(k - 1)} - \frac{c(2n + 1) + 6n + 4k - 5}{4} \right] + \frac{2nk(2n - 1)(k - 1) + 4n^2k^2 - r}{2n(k - 1)},$$

$$B'_1 = \frac{4\mu(2n - 1)}{2 - 2n - 8n\mu + 5\mu} \left[\frac{-8nk(2n - 1)(k - 1) + 4n^2k^2 - r}{2n(k - 1)} + \frac{c(2n + 1) + 6n + 4k - 5 - 8nk}{4} \right] + \frac{-2nk(2n - 1)(k - 1) + 4n^2k^2 - r}{2n(k - 1)}.$$

Thus M is an η -Einstein manifold.

Taking $X = Z = e_i$ in (4.4), we obtain

$$r = 4n^2. \tag{4.7}$$

An h -Weyl semi-symmetric non-Sasakian (k, μ) -space form is an η -Einstein manifold and the scalar curvature in this case is $4n^2$.

Comparing r of (4.7) with (2.10), we obtain

$$c = \frac{5 + 2n - 8k}{2n + 1}. \tag{4.8} \quad \square$$

Definition 4.2. A (k, μ) -space form M is said to be ϕ -Weyl semi-symmetric if $C(X, Y) \cdot \phi = 0$ holds on M .

Theorem 4.2. Let M be a non-Sasakian (k, μ) -space form. If M is ϕ -Weyl semi-symmetric, then M is an η -Einstein manifold.

Proof. Let M be an $(2n + 1)$ -dimensional ϕ -Weyl semi-symmetric non-Sasakian (k, μ) -space form. The condition $C(X, Y) \cdot \phi = 0$ turns into

$$(C(X, Y) \cdot \phi)Z = C(X, Y)\phi Z - \phi C(X, Y)Z = 0, \quad (4.8)$$

for any vector fields X, Y, Z . Using (1.3) and (3.8) in (4.7), we have

$$\begin{aligned} & \frac{1}{4}[(c + 3)\{g(Y, \phi Z)X - g(X, \phi Z)Y - g(Y, Z)\phi X + g(X, Z)\phi Y\} \\ & + (c + 3 - 4k)\{g(X, \phi Z)\eta(Y)\xi - g(Y, \phi Z)\eta(X)\xi - \eta(X)\eta(Z)\phi Y + \eta(Y)\eta(Z)\phi X\} \\ & + (c - 1)\{g(X, \phi^2 Z)\phi Y - g(Y, \phi^2 Z)\phi X - g(X, \phi Z)\phi^2 Y + g(Y, \phi Z)\phi^2 X\} - 2\{g(hX, \phi Z)hY \\ & - g(hY, \phi Z)hX + 2g(X, \phi Z)hY - 2g(Y, \phi Z)hX + 2g(hX, \phi Z)Y - 2g(hY, \phi Z)X \\ & + 2g(hY, \phi Z)\eta(X)\xi - 2g(hX, \phi Z)\eta(Y)\xi - g(\phi hX, \phi Z)\phi hY + g(\phi hY, \phi Z)\phi hX + g(hX, Z)\phi hY \\ & - g(hY, Z)\phi hX + 2g(X, Z)\phi hY - 2g(Y, Z)\phi hX - 2\eta(X)\eta(Z)\phi hY + 2\eta(Y)\eta(Z)\phi hX \\ & - g(\phi hX, Z)\phi^2 hY + g(\phi hY, Z)\phi^2 hX + 2g(hX, Z)\phi Y - 2g(hY, Z)\phi X\} + 4\mu\{g(hY, \phi Z)\eta(X)\xi \\ & - g(hX, \phi Z)\eta(Y)\xi + \eta(X)\eta(Z)\phi hY - \eta(Y)\eta(Z)\phi hX\} - \frac{1}{2n - 1}[S(Y, \phi Z)X - S(X, \phi Z)Y \\ & + g(Y, \phi Z)QX - g(X, \phi Z)QY - S(Y, Z)\phi X + S(X, Z)\phi Y - g(Y, Z)\phi QX + g(X, Z)\phi QY] \\ & + \frac{r}{2n(2n - 1)}[g(Y, \phi Z)X - g(X, \phi Z)Y - g(Y, Z)\phi X + g(X, Z)\phi Y] = 0. \end{aligned} \quad (4.9)$$

Replacing X by ϕX , contracting with W and using (4.9) and symmetry property of h , we obtain,

$$\begin{aligned} & \frac{1}{4}[(c + 3)\{g(Y, \phi Z)g(\phi X, W) - g(\phi X, \phi Z)g(Y, W) + g(Y, Z)g(X, W) - g(Y, Z)\eta(X)\eta(W) \\ & + g(\phi X, Z)g(\phi Y, W)\} + (c + 3 - 4k)\{g(\phi X, \phi Z)\eta(Y)\eta(W) - \eta(Y)\eta(Z)g(X, W) \\ & + \eta(X)\eta(Z)\eta(Y)\eta(W)\} + (c - 1)\{-g(\phi X, Z)g(\phi Y, W) - g(Y, Z)g(X, W) + g(Y, Z)\eta(X)\eta(W) \\ & + \eta(Y)\eta(Z)g(X, W) + g(X, Z)g(Y, W) - \eta(X)\eta(Z)g(Y, W) - g(X, Z)\eta(Y)\eta(W) \\ & - g(Y, \phi Z)g(\phi X, W)\} - 2\{-g(X, Z)g(hY, W) - g(hY, \phi Z)g(h\phi X, W) + 2[-g(X, Z)g(hY, W) \\ & + \eta(X)\eta(Z)g(hY, W)] - 2g(Y, \phi Z)g(h\phi X, W) - 2g(hX, Z)g(Y, W) - 2g(hY, \phi Z)g(\phi X, W) \\ & + 2g(hX, Z)\eta(Y)\eta(W) - g(h\phi X, Z)g(h\phi Y, W) + g(hY, Z)g(hX, W) + g(h\phi X, Z)g(h\phi Y, W) \\ & - g(hY, Z)g(hX, W) + 2g(h\phi X, Z)g(\phi hY, W) - 2g(Y, Z)g(hX, W) + 2\eta(Y)\eta(Z)g(hX, W) \\ & + 2g(h\phi X, Z)g(\phi Y, W) + 2[g(hY, Z)g(X, W) - g(hY, Z)\eta(X)\eta(W)] + g(hX, Z)g(hY, W) \\ & - g(\phi hY, Z)g(hX, W)\} + 4\mu\{g(hX, Z)\eta(Y)\eta(W) - \eta(Y)\eta(Z)g(hX, W)\} \\ & - \frac{1}{2n - 1}[S(Y, \phi Z)g(\phi X, W) - S(\phi X, \phi Z)g(Y, W) + g(Y, \phi Z)S(\phi X, W) - g(\phi X, \phi Z)S(Y, W) \\ & - S(Y, Z)g(\phi^2 X, W) + S(\phi X, Z)g(\phi Y, W) - g(Y, Z)g(\phi Q\phi X, W) + g(\phi X, Z)g(\phi QY, W)] \\ & + \frac{r}{2n(2n - 1)}\{g(Y, \phi Z)g(\phi X, W) - g(\phi X, \phi Z)g(Y, W) - g(Y, Z)g(\phi^2 X, W) \\ & + g(\phi X, Z)g(\phi Y, W)\} = 0. \end{aligned} \quad (4.10)$$

Taking $Y = W = \xi$ in (4.10), we obtain

$$\left[\frac{16nk + 2n^2c + nc + 6n^2 - 5n - 2r}{4n(2n - 1)} \right] g(X, Z) + \left[\frac{-16nk - 2n^2c - nc - 6n^2 + 5n + 2r}{4n(2n - 1)} \right] \eta(X)\eta(Z) + \frac{2\mu n - 8n + 3\mu + 8}{2n - 1} g(hX, Z) = 0. \tag{4.11}$$

Using (2.9) in (4.11), we get

$$S(X, Z) = A'_2 g(X, Z) + B'_2 \eta(X)\eta(Z), \tag{4.12}$$

where

$$A'_2 = \frac{-(8 - 8n + \mu)(16nk + 2n^2c + nc + 6n^2 - 5n - 2r)}{16n(2\mu n - 8n + 3\mu + 8)} + \frac{c(2n + 1) + 6n + 4k - 5}{4},$$

$$B'_2 = \frac{(8 - 8n + \mu)(16nk + 2n^2c + nc + 6n^2 - 5n - 2r)}{16n(2\mu n - 8n + 3\mu + 8)} - \frac{c(2n + 1) + 6n + 4k - 5}{4}.$$

Thus M is an η -Einstein manifold.

Taking $X = Z = e_i$ in (4.12), we obtain

$$r = \frac{(8 - 8n + \mu)(16nk + 2n^2c + nc + 6n^2 - 5n)}{48n - 16\mu n - 22\mu - 48}.$$

A ϕ -Weyl non-Sasakian (k, μ) -space form is an η -Einstein manifold and the scalar curvature in this case is given by

$$r = \frac{(8 - 8n + \mu)(16nk + 2n^2c + nc + 6n^2 - 5n)}{48n - 16\mu n - 22\mu - 48}. \tag{4.13}$$

Comparing r of (4.13) with (2.10), we obtain

$$c = \frac{-12\mu n^2 + 24n^2 - 5\mu n - 64n - 16k\mu n - 80nk - 26\mu k - 16k + 15\mu + 40}{4\mu n^2 - 16n^2 + 7\mu n + 4n + 3\mu + 8}. \quad \square$$

Table 1. Scalar curvature of a non-Sasakian (k, μ) -space form M

S. No.	Curvature tensor	Condition	Scalar curvature
1	Projective curvature tensor	$P(X, Y) \cdot h = 0$	$r = n\{(n + 1)c + 3n + k\}$
2	Projective curvature tensor	$P(X, Y) \cdot \phi = 0$	$r = \frac{1}{4}[16n(n - 1) + 4k(5n + 3)] + \frac{1}{4}[2c(2n + 1) - 14]$
3	Conformal curvature tensor	$C(X, Y) \cdot h = 0$	$r = 4n^2$
4	Conformal curvature tensor	$C(X, Y) \cdot \phi = 0$	$r = \frac{(8 - 8n + \mu)(16nk + 2n^2c + nc + 6n^2 - 5n)}{48n - 16\mu n - 22\mu - 48}$

Competing Interests

The authors declare that they have no competing interests.

Authors' Contributions

All the authors contributed significantly in writing this article. The authors read and approved the final manuscript.

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